

**Semester V**

Course Code	Course Name	Teaching Scheme (Contact Hours)		Credits Assigned		
		Theory	Pract	Theory	Pract	Total
MEC501	Internal Combustion Engines*	04	--	04	--	04
MEC502	Mechanical Measurements and Control*	04	--	04	--	04
MEC503	Heat Transfer*	04	--	04	--	04
MEC504	Dynamics of Machinery	04	--	04	--	04
MEDLO 501X	Department Level Optional Course I	04	--	04	--	04
MEL501	Internal Combustion Engines	--	02	--	01	01
MEL502	Mechanical Measurements and Control	--	02	--	01	01
MEL503	Heat Transfer	--	02	--	01	01
MEL504	Dynamics of Machinery	--	02	--	01	01
MEL505	Manufacturing Sciences Lab	--	02	--	01	01
MEL506	Business Communication and Ethics	--	02 <sup>s</sup> +02	--	02	02
Total		20	14	20	07	27

Course Code	Course Name	Examination Scheme							
		Theory					Term Work	Pract/ Oral	Total
		Internal Assessment			End Sem Exam	Exam Duration (Hrs)			
		Test1	Test 2	Avg					
MEC501	Internal Combustion Engines	20	20	20	80	03	--	--	100
MEC502	Mechanical Measurements and Control	20	20	20	80	03	--	--	100
MEC503	Heat Transfer	20	20	20	80	03	--	--	100
MEC504	Dynamics of Machinery	20	20	20	80	03	--	--	100
MEDLO 501X	Department Level Optional Course I	20	20	20	80	03	--	--	100
MEL501	Internal Combustion Engines	--	--	--	--	--	25	25	50
MEL502	Mechanical Measurements and Control	--	--	--	--	--	25	25	50
MEL503	Heat Transfer	--	--	--	--	--	25	25	50
MEL504	Dynamics of Machinery	--	--	--	--	--	25	25	50
MEL505	Manufacturing Sciences Lab	--	--	--	--	--	25	--	25
MEL506	Business Communication and Ethics	--	--	--	--	--	50	--	50
Total				100	400		175	100	775

<sup>§</sup>Theory classes shall be conducted for entire class

Course Code	Department Level Elective Course I
MEDLO5011	Press Tool Design
MEDLO5012	Machining Sciences and Tool Design
MEDLO5013	Design of Jigs and Fixtures

Course Code	Course/Subject Name	Credits
<b>MEC501</b>	<b>Internal Combustion Engines*</b>	<b>4</b>

### Objectives

1. To familiarize with the working of S.I. and C.I. engines and its important systems
2. To acquaint with the various methods for measurement of engine performance
3. To provide insight into the harmful effects of engine pollutants and its control
4. To familiarise with the latest technological developments in engine technology

### Outcomes: Learner will be able to...

1. Demonstrate the working of different systems and processes of S.I. engines
2. Demonstrate the working of different systems and processes of C.I. engines
3. Illustrate the working of lubrication, cooling and supercharging systems.
4. Analyse engine performance
5. Illustrate emission norms and emission control
6. Comprehend the different technological advances in engines and alternate fuels

Module	Detailed Contents	Hrs.
<b>01</b>	<b>Introduction</b> Classification of I.C. Engines; Parts of I.C. Engine and their materials, Cycle of operation in Four stroke and Two-stroke IC engines and their comparative study; Fuel air cycles and their analysis, Actual working cycle, Valve Timing Diagram. LHR Engines, Homogeneous charge compression Ignition, Rotary engine-Six stroke engine concept	06
<b>02</b>	<b>S.I. Engines</b> <b>Fuel Supply System:</b> Spark ignition Engine mixture requirements, Fuel-Air ratio, Simple carburettor and auxiliary circuits (excluding mathematical analysis of carburettors) Injection systems: Single-point and Multipoint injection, Gasoline Direct Injection <b>Ignition System:</b> Battery Ignition System, Magneto Ignition System, Functions and working of ignition coil, spark plug, contact breaker point, Requirements and working of Ignition advance mechanisms; mechanical and vacuum, Electronic Ignition Systems; Capacitor Discharge Ignition System, Transistorized Coil Assisted Ignition System, Transistor Ignition system with contactless breaker <b>Combustion :</b> Combustion phenomenon in SI Engines, Ignition delay, Flame propagation, Pressure-Crank angle diagram, Abnormal combustion, Auto ignition, Detonation and Knocking, Factors affecting combustion and detonation, Types of combustion chambers	12
<b>03</b>	<b>Compression Ignition Engines</b> <b>Fuel Injection Systems:</b> Air injection systems, Airless/solid injection systems, Common rail, individual pump, distributor and unit systems. Injection pumps, Fuel injector, Types of nozzle, Electronically controlled unit fuel injection system <b>Combustion:</b> Combustion phenomenon in C I engines, Stages of combustion, Delay period, Knocking, Pressure-Crank angle diagram, Factors affecting combustion and knocking, Types of combustion chambers	10
<b>04</b>	<b>Engine lubrication:</b> Types of lubricants and their properties, SAE rating of lubricants, Types of lubrication systems <b>Engine Cooling:</b> Necessity of engine cooling, disadvantages of overcooling, Cooling systems and their comparison: Air cooling, Liquid cooling <b>Supercharging/Turbo-charging:</b> Objectives, Limitations, Methods and Types, Different arrangements of turbochargers and superchargers	06

05	<b>Engine Testing and Performance</b> Measurement of Brake Power, Indicated Power, Frictional Power, Fuel Consumption, Air flow, BMEP, Performance characteristic of SI and CI Engine Effect of load and speed on Mechanical, Indicated Thermal, Brake Thermal and Volumetric efficiencies, Heat balance sheet. <b>Engine Exhaust Emission and its control</b> Constituents of exhaust emission at its harmful effect on environment and human health, Formation of NO <sub>x</sub> , HC, CO and particulate emissions, Methods of controlling emissions; Catalytic convertors, particulate traps, Exhaust Gas Recirculation, EURO and BHARAT norms.	10
06	<b>Alternative Fuels</b> Alcohol - Hydrogen - Natural Gas and Liquefied Petroleum Gas – Biodiesel- Biogas - Producer Gas - Properties - Suitability - Engine Modifications - Merits and Demerits as fuels. <b>Basics of Electronic Engine Controls:</b> Electronic Control module (ECM), Inputs required and output signals from ECM, Sensors: Throttle Position, Inlet Air Temperature, Coolant Temperature, Crankshaft Position, Camshaft Position, Mass Air flow and Exhaust Gas Oxygen sensors, their construction and importance in ECM. Electronic Spark control, Air Management system, Idle speed control	04

### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of content and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the syllabus.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the syllabus**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

#### **References:**

1. Internal Combustion Engines, Willard W.Pulkrabek, Pearson Education.
2. Internal Combustion Engines, Shyam Agrawal, New Age International
3. Internal Combustion Engine, Mathur and Sharma
4. Internal Combustion Engines, Mohanty, Standard Book House
5. Internal Combustion Engine, Gills and Smith
6. Internal Combustion Engines Fundamentals, John B. Heywood , TMH
7. Internal Combustion Engines, Gupta H N, 2<sup>nd</sup> ed, PHI
8. Internal Combustion Engine, V Ganesan, TMH
9. Introduction to Internal Combustion Engines, Richard Stone, Palgrave Publication, 4<sup>th</sup> Edition
10. Internal Combustion Engine, S.L. Beohar
11. Internal Combustion Engine, P.M Heldt.
12. Internal Combustion Engines, V.L. Maleeve
13. Internal Combustion Engine, E.F. Oberi.
14. Internal Combustion Engine by Domkundwar

Course Code	Course/Subject Name	Credits
<b>MEC502</b>	<b>Mechanical Measurement and Control*</b>	<b>4</b>

### Objectives

1. To impart knowledge of architecture of the measurement system
2. To deliver working principle of mechanical measurement system
3. To study concept of mathematical modelling of the control system
4. To acquaint with control system under different time domain

### Outcomes: Learner will be able to...

1. Classify various types of static characteristics and types of errors occurring in the system.
2. Classify and select proper measuring instrument for linear and angular displacement
3. Classify and select proper measuring instrument for pressure and temperature measurement
4. Design mathematical model of system/process for standard input responses
5. Analyse error and differentiate various types of control systems and time domain specifications
6. Analyse the problems associated with stability

Module	Contents	Hours
<b>01</b>	1.1 Significance of Mechanical Measurements, Classification of measuring instruments, generalized measurement system, types of inputs: Desired, interfering and modifying inputs. 1.2 Static characteristics: Static calibration, Linearity, Static Sensitivity, Accuracy, Static error, Precision, Reproducibility, Threshold, Resolution, Hysteresis, Drift, Span & Range etc. 1.3 Errors in measurement: Types of errors, Effect of component errors, Probable errors.	<b>08</b>
<b>02</b>	2.1 <b>Displacement Measurement:</b> Transducers for displacement, displacement measurement, potentiometer, LVDT, Capacitance Types, Digital Transducers (optical encoder) , Nozzle Flapper Transducer 2.2 <b>Strain Measurement:</b> Theory of Strain Gauges, gauge factor, temperature Compensation, Bridge circuit, orientation of strain gauges for force and torque, Strain gauge based load cells and torque sensors 2.3 <b>Measurement of Angular Velocity:</b> Tachometers, Tachogenerators, Digital tachometers and Stroboscopic Methods. 2.4 <b>Acceleration Measurement:</b> theory of accelerometer and vibrometers, practical accelerometers, strain gauge based and piezoelectric accelerometers	<b>08</b>
<b>03</b>	3.1 <b>Pressure Measurement:</b> Elastic pressure transducers viz. Bourdon tubes, diaphragm, bellows and piezoelectric pressure sensors, High Pressure Measurements, Bridge man gauge. Vacuum measurement: Vacuum gauges viz. McLeod gauge, Ionization and Thermal Conductivity gauges 3.2 <b>Flow Measurement:</b> Bernoulli flowmeters, Ultrasonic Flowmeter, Magnetic flow meter, rotameter 3.3 <b>Temperature Measurement:</b> Electrical methods of temperature measurement Resistance thermometers, Thermistors and thermocouples, Pyrometers 3.4 <b>Sensitivity analysis of sensor-</b> influence of component variation 3.5 <b>Signal conditioning:</b> Amplifier, Conversion, Filtering, Impedance Buffering, Modulation / Demodulation, Linearization, Grounding and Isolation	<b>08</b>
<b>04</b>	4.1 Introduction to control systems, Classification of control system. Open loop and closed loop systems. 4.2 Mathematical modelling of control systems, concept of transfer function, Block diagram algebra	<b>06</b>
<b>05</b>	5.1 <b>Transient and steady state analysis of first and second order system.</b> Time Domain specifications. Step response of second order system. Steady-state error, error coefficients, steady state analysis of different type of systems using step, ramp and parabolic inputs	<b>06</b>

06	<b>Stability analysis</b> 6.1 Introduction to concepts of stability, The Routh criteria for stability 6.2 Experimental determination of frequency response, Stability analysis using Root locus, Bode plot and Nyquist Plots 6.3 State space modeling 6.4 Process control systems, ON-OFF control. P-I-D Control	12
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### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of content and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the syllabus.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the syllabus**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

### **References**

1. Measurement Systems: Applications and Design, by EO Doebelin, 5<sup>th</sup> Edition, *McGraw Hill*
2. Mechanical Engineering Measurements, A K Sawhney, *Dhanpat Rai & Sons, New Delhi*
3. Instrumentation & Mechanical Measurements, A K Thayal
4. Control System Engineering by Nagrath IJ and Gopal M, *Wiley Eastern Ltd.*
5. Modern Control engineering: by KOgata, *Prentice Hall*
6. Control systems by DhaneshManik, Cengage Learning
7. Engineering Metrology and Measurements by N V Raghavendra and L Krishnamurthy, Oxford University Press
8. Instrumentation and Control System, W. Bolton, Elsevier
9. Experimental Methods for Engineers by J P Holman, McGraw Hills Int. Edition
10. Engineering Experimentation by EO Doebelin, McGraw Hills Int. Edition
11. Mechanical Measurements by S P Venkateshan, Ane books, India

Course Code	Course/Subject Name	Credits
<b>MEC 503</b>	<b>Heat Transfer*</b>	<b>04</b>

### Objectives

1. To Study basic heat transfer concepts applicable for steady state and transient conditions
2. To Study mathematical modelling and designing concepts of heat exchangers

### Outcomes: Learner will be able to...

1. Identify the three modes of heat transfer (conduction, convection and radiation).
2. Illustrate basic modes of heat transfer
3. Develop mathematical model for each mode of heat transfer
4. Develop mathematical model for transient heat transfer
5. Demonstrate and explain mechanism of boiling and condensation
6. Analyse different heat exchangers and quantify their performance

Module	Detailed Contents	Hrs.
<b>01</b>	<b>Basic concepts of heat transfer:</b> Define heat transfer and its importance in engineering applications, Difference between heat transfer and Thermodynamics, Physical Mechanism of modes of heat transfer, Governing laws of heat transfer, Conduction mode: Thermal conductivity, Thermal diffusivity, Convection mode: Free and Forced convection, Heat transfer Coefficient, Radiation mode: Emissivity, transmissivity, reflectivity, absorptivity, Black body, Grey body, Opaque body, Steady and unsteady heat transfer, One dimensional, two dimensional and three dimensional heat transfer, Thermal resistance concept in heat transfer, Thermal contact resistance	04
<b>02</b>	<b>Conduction:</b> Assumptions in heat conduction, Generalized heat conduction equation in rectangular, cylindrical coordinates, Initial and boundary conditions, Steady state heat conduction through plane wall, Composite wall, cylinder, composite cylinder wall, sphere, Internal Heat generation concept, Heat conduction with heat generation in plane wall, solid cylinder and solid sphere, Critical radius of insulation in cylinder and sphere	08
<b>03</b>	<b>Heat transfer from Extended Surface:</b> Types of extended surface and its significance, Governing differential equation for fin and its solution, Fin performance: Fin effectiveness and Fin efficiency, Thermo Well <b>Unsteady state heat transfer:</b> Applications of unsteady state heat transfer, Lumped system Analysis, Criteria for lumped system analysis: characteristic length, Biot Number, Thermal time constant and Response of a thermocouple, Heisler Charts <b>Numerical methods in heat transfer:</b> Significance of numerical methods in heat transfer, Finite difference formulation of differential equations, One-dimensional heat conduction.	08
<b>04</b>	<b>Convection:</b> Determination of heat transfer coefficient, Dimensional Analysis, Dimensionless numbers in free and forced convection and their significance <b>External Flow:</b> Velocity Boundary layer and Thermal Boundary layer, Laminar and turbulent flow over a flat plate, Flow across cylinder and sphere, Flow across bank of tubes <b>Internal Flow:</b> Velocity Boundary layer and Thermal Boundary layer, Laminar and Turbulent flow in tubes, General thermal analysis: Constant heat flux and constant surface temperature	10
<b>05</b>	<b>Radiation:</b> Basic laws of radiation, Black body radiation, Planck's law, Kirchhoff's law, Wein displacement law, Lambert cosine law, Radiation intensity, Radiation heat exchange between black bodies, Shape factor algebra, Radiation heat exchange between nonblack bodies, Electrical network approach for radiation heat exchange: Radiosity and irradiation, Radiation shield	08
<b>06</b>	<b>Boiling and Condensation:</b> Boiling heat transfer, Pool boiling: different regimes and pool boiling curve, Flow boiling: Different Regimes and Boiling curve, Condensation heat transfer, Film condensation, Dropwise Condensation <b>Heat Exchangers:</b> Types of heat exchangers, Overall heat transfer coefficient, Fouling factor, Analysis of heat exchangers, LMTD, Effectiveness –NTU method, Correction factor, Effectiveness of heat exchangers <b>Heat Pipe:</b> Introduction and application	10

**Assessment:****Internal Assessment for 20 marks:**

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**End Semester Examination:**

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3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

**ReferenceBooks:**

1. Introduction to thermodynamics and Heat transfer by Yunus A Cengel 2<sup>nd</sup> Edition, McGraw Hill International
2. Fundamentals of Heat and Mass Transfer by F P Incropera and D P deWitt, Wiley India
3. Heat Transfer by P S Ghoshdastidar, 2<sup>nd</sup> Edition, Oxford University Press
4. Heat and Mass Transfer, by R Rudramoorthy and L Malaysamy, 2<sup>nd</sup> Edition, PEARSON
5. Heat Transfer by J P Holman, McGraw Hill
6. Heat Transfer by S P Sukhatme, University Press
7. Heat and Mass Transfer by PK Nag, TMH
8. Heat and Mass Transfer by Mahesh Rathod, Laxmi Publications
9. Heat and Mass Transfer by R K Rajput, S Chand and company

Course Code	Course/Subject Name	Credits
<b>MEC504</b>	<b>Dynamics of Machinery*</b>	<b>4</b>

**Objectives:**

1. To acquaint with working principles and applications of Governors / Gyroscope
2. To study static and dynamic force analysis in the mechanisms
3. To familiarise with basics of mechanical vibrations
4. To study the balancing of mechanical systems

**Outcomes:** Learner will be able to...

1. Demonstrate working Principles of different types of governors and Gyroscopic effects on the mechanical systems
2. Illustrate basic of static and dynamic forces
3. Determine natural frequency of element/system
4. Determine vibration response of mechanical elements / systems
5. Design vibration isolation system for a specific application
6. Demonstrate basic concepts of balancing of forces and couples

Module	Details	Hrs.
<b>1</b>	<b>Governors and Gyroscopes:</b> 1.1 <b>Governors:</b> Introduction to Centrifugal and Inertia governors, Force analysis of governors- Porter and Hartnell governors, Performance characteristics of governors, Governors effort and power 1.2 <b>Gyroscope:</b> Introduction, Gyroscopic couple and its effect on spinning bodies, naval ships during steering, pitching, rolling and their stabilization. Effect of gyroscopic and centrifugal couples, permissible speeds on curve paths, gyroscopic effect due to lateral misalignment of rigid disc mounted on shaft.	<b>09</b>
<b>2</b>	2.1 <b>Static and Dynamic force analysis,</b> in slider crank mechanism (neglecting mass of connecting rod and crank), Engine force analysis, Turning moment on crank shaft 2.2 <b>Dynamically equivalent systems,</b> to convert rigid body in to two mass with and without correction couple	<b>06</b>
<b>3</b>	3.1 <b>Basic Concepts of Vibration:</b> Vibration and oscillation, causes and effects of vibrations, Vibration parameters - springs, mass, damper, damper models, Motion- periodic, non-periodic, degree of freedom, static equilibrium position, vibration classification, steps involved in vibration analysis 3.2 <b>Free Undamped Single Degree of Freedom Vibration System:</b> Longitudinal, transverse, torsional, vibration system, methods for formulation of differential equations by Newton, Energy, Lagrangian and Rayleigh's method	<b>08</b>
<b>4</b>	4.1 <b>Free Damped Single Degree of Freedom Vibration System:</b> Viscous damped system - under damped, critically damped, over damped; Logarithmic decrement; Coulomb's damping 4.2 <b>Equivalent Single Degree of Freedom Vibration System:</b> Conversion of multi-springs, multi masses, multi-dampers into a single spring and damper with linear or rotational co-ordinate system, Introduction to free multi-degree of freedom vibration systems	<b>07</b>
<b>5</b>	5.1 <b>Forced Single Degree of Freedom Vibratory System:</b> Analysis of linear and torsional systems subjected to harmonic force excitation and harmonic motion excitation (excluding elastic damper) 5.2 <b>Vibration Isolation and Transmissibility:</b> Force Transmissibility, motion transmissibility, typical isolators & mounts.	<b>10</b>



	<b>5.3 Vibration Measuring instruments:</b> Principle of seismic instruments, vibrometer, accelerometer - undamped and damped, Introduction to conditioning monitoring and fault diagnosis	
<b>6</b>	<b>6.1 Rotor Dynamics:</b> Critical speed of single rotor, undamped and damped <b>6.2 Balancing:</b> Static and Dynamic balancing of multi rotor system, balancing of reciprocating masses in In-line engines, V-engines (excluding other radial engines)	<b>08</b>

### **Assessment:**

#### **Internal Assessment for 20 marks:**

##### **Consisting Two Compulsory Class Tests**

First test based on approximately 40% of content and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the syllabus.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
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3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

#### **References:**

1. Theory of Machines Thomas Bevan CSB Publishers & Distributors
2. Theory of Machines by Jagdishlal Metropolitan Book New Delhi, Company, Daryaganj, Delhi
3. Theory of Machines by S.S.Ratan Tata McGraw Hill , New Delhi
4. Theory of Machines by P.L.Bellaney Khanna publication, NewDelhi
5. Theory of Machines and Mechanisms by John J Uicker, Gordon R Pennock and Joseph E Shigley, Oxford University Press
6. Theory of Vibration with Applications, by W. Thomson, 2nd edition, Pearson Education
7. Mechanical Vibrations by S.S.Rao, fourth edition, Pearson Education
8. Mechanical Vibrations by G.K.Grover
9. Fundamentals of Mechanical Vibration by S.Graham Kelly, Tata McGraw Hill
10. Principles of Vibration by Benson H Tongue, 2<sup>nd</sup> Edition, Oxford University Press
11. Vibration Analysis by P. Srineevasan, TMH
12. Mechanical Vibrations- Schaum's outline series, William W.Seto, McGraw Hill
13. Theory and Practice of Mechanical Vibrations by J S Rao and K Gupta, New Age International
14. Elements of Vibration Analysis by Leonard Meirovitch, McGraw- Hill, New York

Course Code	Course/Subject Name	Credits
<b>MEDLO5011</b>	<b>Press Tool Design</b>	<b>4</b>

**Objectives:**

1. To acquaint with various press working operations for mass production of sheet metal components
2. To familiarise with sheet metal working techniques for design of press tools
3. To inculcate knowledge about scrap minimization, safety aspects and automation in press working

**Outcomes:** Learner will be able to....

1. Demonstrate various press working operations for mass production of sheet metal parts
2. Identify press tool requirements to build concepts pertaining to design of press tools
3. Prepare working drawings and setup for economic production of sheet metal components
4. Select suitable materials for different elements of press tools
5. Illustrate the principles and blank development in bent & drawn components
6. Elaborate failure mechanisms of pressed components, safety aspects and automation in press working

Module	Contents	Hours
<b>1</b>	<b>Introduction to Press Working –</b> 1.1 Classification of common Press working operations, Benefits and limitations of using Press tools. Applications of pressed parts/components. 1.2 Theory of Shearing in Press Working. Optimum Cutting clearance & its effect on tolerances of pressed components. Construction of Basic shearing die. Functions of different elements of a press tool. Methods of feeding the strip/coil material.	<b>08</b>
<b>2</b>	<b>Design and Calculations of Piercing &amp; Blanking Die–</b> 2.1 Calculations for Economic Strip Layout, Calculations of Cutting force and Stripping force, Recommending minimum tonnage of a press. Centre of Pressure (its importance and calculation) 2.2 Design aspects of Press tool elements viz. Punches & methods of retaining punches, Die block, Stripper, Pilot, etc. Methods of reducing cutting loads on press tools 2.3 Different types Die sets and its selection	<b>14</b>
<b>3</b>	<b>3.1 Selection of Material &amp; Hardware –</b> Selection and arrangement of Hardware used in Press tools. Selection of steels and its hardness for different elements of Press tools.	<b>03</b>
<b>4</b>	<b>Bending and Drawing-</b> 4.1 Theory of Bending, Spring back and measures to control it, Calculations for Blank development of Simple Bent components, Minimum bend radius, Types of Bending dies 4.2 Theory of Drawing, Metal flow in Drawing & forming operations; reduction ratio and redrawing limits, draw clearance, drawing and blank holding forces for cylindrical draws only. Blank development of Cup 4.3 Defects in drawn as well as bent parts, Presses selection for drawing/forming operations 4.4 Basic construction and working of Bending and Drawing dies	<b>12</b>
<b>5</b>	<b>5.1 Miscellaneous Dies-</b> Basic construction & working of Shaving dies, Trimming dies, Compound dies, Combination dies, Coining dies, Embossing dies, Simple Progressive & Compound Progressive dies	<b>05</b>
<b>6</b>	<b>Selection of Presses and its setting –</b> 6.1 Selection of Press and Press setting for Shearing, Bending, Progressive and Drawing dies, Equipment for Sheet metal operations (Basics only), Overloading of presses (load, energy considerations) 6.2 Introduction to Automation & Safety in Press shop	<b>06</b>

### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved.**

#### **References**

1. Die Design Fundamentals by J. R. Paquin, Industrial Press
2. Techniques of Press Working Sheet Metal by D F Eary and E A Reed
3. Press Tools Design and Construction by P H Joshi, S Chand Publishing
4. Tool Design by C. Donaldson and V C Goold, TMH
5. Production Engineering by P. C. Sharma, S Chand Publishing
6. Metal working ASM Handbook

Course Code	Course/Subject Name	Credits
<b>MEDLO5012</b>	<b>Machining Sciences And Tool Design</b>	<b>4</b>

### Objectives

1. To familiarise with the basic concepts of machining science like mechanics of machining, tool wear, tool life and surface roughness.
2. To familiarise with various single and multipoint cutting tools designing processes
3. To study the economics of machining process

### Outcomes: Learner will be able to...

1. Calculate the values of various forces involved in the machining operations
2. Design various single and multipoint cutting tools
3. Analyse heat generation in machining operation and coolant operations
4. Illustrate the properties of various cutting tool materials and hence select an appropriate tool material for particular machining application
5. Demonstrate the inter-relationship between cutting parameters and machining performance measures like power requirement, cutting time, tool life and surface finish
6. Analyse economics of machining operations

Module	Details	Hrs.
<b>01</b>	<p><b>1.1 Metal Cutting Theory:</b> Orthogonal and oblique cutting, various types of chips, Mechanics of orthogonal steady state metal cutting, shear plane and shear plane angle, Merchant's force circle, stresses, shear strain, velocity relations, rate of strain, energy considerations, Concept of specific power consumption in machining, Ernst and Merchant's model &amp; modified model for orthogonal cutting, Lee and Shaffer model, Analytical modelling of machining operations, mechanistic modelling of machining, slip line field analysis, finite element analysis, modelling of material properties</p> <p><b>1.2 Dynamometry:</b> Dynamometer requirements, force measurement, electric transducers, strain gage lathe dynamometer, strain rings, milling dynamometer, drilling dynamometer, surface grinding dynamometer, piezoelectric dynamometry</p>	<b>10</b>
<b>02</b>	<p><b>2.1 Temperatures in metal cutting and cutting fluids:</b> Heat generation in metal cutting, heat transfer in a moving material, temperature distribution in metal cutting, temperature in primary deformation zone, temperature in secondary deformation zone, effect of cutting speed on temperature, prediction of temperature distribution in machining, measurement of cutting temperature, work-tool thermocouple, direct thermocouple measurement, radiation methods, hardness and microstructure changes in steel tools</p> <p>Cutting fluid types, the action of coolants, the action of lubricants, characteristics of an efficient lubricant in metal cutting, application methods of cutting fluid, cutting fluid maintenance and environmental considerations, disposal of cutting fluids, dry cutting and minimum quantity lubrication, cryogenic cooling</p>	<b>06</b>
<b>03</b>	<p><b>Cutting tool materials and machining induced surface integrity</b></p> <p><b>3.1</b> Properties of cutting tool materials, Major tool material types, Plain carbon steel, high speed steel, cast alloys, cemented tungsten carbide, titanium carbides, ceramic and cermet tools, synthetic diamond, polycrystalline diamond (PCD), cubic boron nitride (CBN), coated tools</p> <p><b>3.2</b> Measurement and specification of surface finish, primary cutting edge finish, fracture roughness, BUE formation and its influence on finish, secondary cutting edge finish,</p>	<b>06</b>

	geometrical contribution to roughness, edge finishing, residual stress and micro hardness	
<b>04</b>	<b>4.1 Tool life and machining economics:</b> Definition, flank wear and crater wear, criteria for tool failure, effect of cutting parameters and tool geometry on tool life, Taylor's tool life equation, Experimental methods to find Taylor exponents, Components of product cost, Optimum cutting velocity for minimum cost of production and maximum production rate	<b>06</b>
<b>05</b>	<b>5.1 Design of single point cutting tools :</b> Different systems of tool nomenclature like MRS, ORS and NRS, Interrelationship among different systems of nomenclature for tool angles, Constructional features of solid tool, tipped tools, mechanically held regrind able insert type tools and throw away tip type tools, Design of shanks, cutting tip and chip breakers for HSS and Carbide tools, ISO coding system for tipped tools and tool holders	<b>08</b>
<b>06</b>	<b>6.1 Design of multi point cutting tools :</b> Various types such as flat form tool, tangential form tool, circular form tool, constructional details and fields of application, Profile design of flat and circular form tools, Broach nomenclature, design steps for circular pull type, key way and spline broaches, Design of face and peripheral milling cutters	<b>10</b>

### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved.**

#### **References**

1. Fundamentals of Metal Machining and Machine Tools, Third Edition by Winston A. Knight, Geoffrey Boothroyd, CRC press Taylor and Francis group
2. Metal Cutting Principles by Milton Clayton Shaw, 2<sup>nd</sup> Edition, Oxford University Press
3. Cutting Tools by P H Joshi, A H Wheeler Publishing Co Ltd
4. ASM Handbook, Vol. 16: Machining by Joseph R. Davis, 9<sup>th</sup> Edition, ASM International
5. Fundamentals of Metal Cutting and Machine Tools by B. L. Juneja, G. S. Sekhon and Nitin Seth, 2<sup>nd</sup> Edition, New Age International
6. Metal Cutting Theory and Cutting Tool Design, by V. Arshinov and G. Alekseev, Mir publishers, Moscow
7. Typical Examples and Problems in Metal Cutting and Tool Design, by N. Nefedov and K. Osipov, Mir publishers, Moscow

Course Code	Course/Subject Name	Credits
<b>MEDLO5013</b>	<b>Design of Jigs and Fixtures</b>	<b>4</b>

## Objectives

1. To acquaint with the concepts of planning and writing sequence of operations
2. To acquaint basics of identification and selection of location and clamping points on work-piece
3. To familiarise design principles in designing simple productive and cost effective jigs and fixtures

## Outcomes: Learner will be able to...

1. Write methodically, the sequence of operations of simple work-piece
2. Identify and select locating and clamping points on work-piece
3. Demonstrate construction of drill jig
4. Illustrate construction of milling fixture
5. Identify appropriate combination of tools, jigs and fixture, suitable for a particular machining operation
6. Design assembly of jigs and fixtures on simple work-piece

Module	Details	Hrs
<b>01</b>	<b>1.1 Introduction to Tool Design</b> Production Tooling's Jigs, Fixtures and their difference, their requirement(accuracy, machinability, quantity modifications so as to assist production, Interchange ability, Simplicity, Swarf disposal, Handling, Ease of operation, Skill reduction, Cost reduction), Analysis for Operation planning, sequencing of operations.	<b>08</b>
<b>02</b>	<b>Basic Construction of Jig &amp; Fixture</b> <b>1.1 Location &amp; Locating Devices</b> Locating principles: Degrees of freedom, Redundant location, Fool-proofing, nesting, Locators: locators that control work piece on flat surfaces, location of cylindrical surfaces, conical locators, centralizers. <b>1.2 Clamping &amp; clamping Devices</b> Requirement of clamping system, Position of clamps, Types of clamps, Clamping devices; examples of typical clamps(multiple clamping and equalizing devices, quick acting clamping mechanisms such as link, toggle, cam, eccentric, pneumatic, hydraulic and electric devices), Component distortion under clamping and cutting forces, Material used for different clamping devices of jigs/fixture and recommended hardness	<b>10</b>
<b>03</b>	<b>3.1 Construction of Drill Jig</b> Introduction, Selection of location, supporting and clamping faces /points, cutting tools and means of guiding and supporting Jigs, various types of Jig Bushes, Commonly used drill jigs, Case Study on Design of Drill Jig	<b>10</b>
<b>04</b>	<b>4.1 Construction of Milling fixture</b> Introduction, Selection of location, supporting and clamping faces /points choice, tool setting block and Tennon's, Case Study on Design of Milling Fixture	<b>08</b>
<b>05</b>	<b>5.1 Introduction to Commonly used Fixtures</b> Turning Fixture (Chucks, collets, Mandrels) Grinding Fixture, Broaching Fixture, and Welding Fixture	<b>08</b>
<b>06</b>	<b>6.1 Indexing Jig &amp; Fixture</b> Introduction, Application of indexing, Essential features of an indexing jig /fixture, Indexing Devices	<b>04</b>

### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

#### **References**

1. Jig and Fixture Design Manual, Erik K. Henrikson, Industrial Press
2. An introduction to jig and tool Design, MH A Kempster, 3<sup>rd</sup> Edition, ELBS
3. Jigs and Fixture, P. H. Joshi, TMH
4. Tool design, C. Donaldson, George H. Lecain, V.C. Goold, TMH
5. Jigs and Fixture Handbook, A.K. Goroshkin, Mir Publication
6. Jigs and Fixture, ASTME
7. Non- Standards Calming Devices, Hiran E. Grant TMH, New Delhi

Subject Code	Subject Name	Credits
<b>MEL 501</b>	<b>Internal Combustion Engines Lab</b>	<b>01</b>

### Objectives:

1. To familiarise concept of thermal conductivity, heat transfer coefficient through experiments
2. To familiarise experimental verification of the concepts of heat transfer

### Outcomes: Learner will be able to...

1. Dismantle engine assembly
2. Overhaul and Assemble engine components
3. Perform load test/speed test on engine setup
4. Calculate performance of multi cylinder engine
5. Analyse engine performance and draw heat balance sheet
6. Perform exhaust gas analysis

### Part A: Dismantle, overhaul and assemble the following

1. 2 Stroke/ 4 Stroke Engines
2. Carburettor
3. Ignition system
4. Fuel injection system

### Part B: Performing experiments on engine test rigs

1. Morse Test on petrol engine
2. Speed Test on petrol or/and diesel engine
3. Load Test on diesel engine (engines)
4. Heat Balance test on diesel or petrol engines
5. Experimental determination of Air fuel ratio and volumetric efficiency of the engine
6. Exhaust Gas/Smoke analysis of S.I./ C.I. engines
7. Effect of Supercharging on Performance Characteristics of an engine

### Term Work

Term work shall consist of minimum 6 exercises, from the list, out of which minimum 4 must be actual experiments from Part B and 1 case study/report (in group of not more than 3 students) on latest trends/developments in IC Engines.

The distribution of marks for term work shall be as follows:

1. Laboratory work (Exercises) : **15 marks**
2. Case study: **05 marks**
3. Attendance: **05 marks**

### End Semester Practical/Oral Examination:

1. Pair of Internal and External Examiner should conduct practical/viva based on contents
2. Distribution of marks for practical/viva examination shall be as follows:
 

Practical performance	15 marks
Oral	10 marks
3. Evaluation of practical examination to be done based on the experiment performed and the output of the experiment during practical examination
4. Students work along with evaluation report to be preserved till the next examination



Course Code	Course/Subject Name	Credits
<b>MEL 502</b>	<b>Mechanical Measurement and Control</b>	<b>1</b>

### Objectives

1. To study calibration of different measuring instruments
2. To study working of mechanical measurement system
3. To familiarise with different types of control systems

### Outcomes: Learner will be able to...

1. Calibrate displacement sensors
2. Calibrate pressure and vacuum gauges
3. Measure torque using strain gauges
4. Identify system/process characteristics for standard input responses
5. Identify various types of control systems and time domain specifications
6. Analyse the problems associated with stability

### List of Experiments

Sr. No.	Topic
1	Calibration of Displacement sensors like LVDT, Potentiometers etc.
2	Calibration of Pressure Gauges
3	Calibration of Vacuum Gauges
4	Torque measurement using strain gauges
5	Calibration of tachometers
6	Vibration Measurement & Calibration of Accelerometers.
7	Experiments on feedback control systems and servomechanisms
8	System Identification of any one of the sensor
9	Experiment on frequency response system identification
10	Experiment on transient state response of a control system.
11	Experiment on design of PID controller for a system.

- (a) Design based experiments shall be encouraged using standard National Instrument/ texas instrument/ dSPACEGmbh/ Arduino or any other platform). **Learners (in a group) may be encouraged for Project Based Learning. Appropriate weightage may be given in term work assessment**

### Term Work

Term work shall consist of minimum 8 experiments (04 from the measurement group and 4 from the control group),

The distribution of marks for term work shall be as follows:

- Laboratory work (Experiments) : **15 marks**
- Design based experiment: **05 marks**
- Attendance: **05 marks**

### End Semester Practical/Oral Examination:

1. Pair of Internal and External Examiner should conduct practical/viva based on contents
2. Distribution of marks for practical/viva examination shall be as follows:
 

Practical performance	15 marks
Oral	10 marks
3. Evaluation of practical examination to be done based on the experiment performed and the output of the experiment during practical examination
4. Students work along with evaluation report to be preserved till the next examination

Subject Code	Subject Name	Credits
<b>MEL 503</b>	<b>Heat Transfer Lab</b>	<b>01</b>

**Objectives:**

1. To familiarise concept of thermal conductivity, heat transfer coefficient through experiments
2. To familiarise experimental verification of the concepts of heat transfer

**Outcomes:** Learner will be able to...

1. Estimate thermal conductivity of metals/non metals/liquids
2. Compute heat transfer coefficient in natural as well forced convection
3. Measure emissivity of grey body
4. Quantify fin effectiveness/efficiency
5. Analyse heat exchanger performance
6. Demonstrate energy balance for heat exchanger

The laboratory experiments should be based on the following:

Expt.No	Name of Experiments	Time
1	<b>Conduction: (Any Two)</b> <ol style="list-style-type: none"> <li>1. Measurement of thermal conductivity of metal rod</li> <li>2. Measurement of thermal conductivity of insulating material</li> <li>3. Measurement of thermal conductivity of liquid</li> <li>4. Determination of contact resistance</li> <li>5. Effect of area on heat transfer</li> </ol>	2Hrs
2	<b>Convection: (Any One)</b> <ol style="list-style-type: none"> <li>1. Measurement of heat transfer coefficient in natural convection</li> <li>2. Measurement of heat transfer coefficient in forced convection</li> <li>3. Comparison of heat transfer coefficient of free and forced convection</li> </ol>	2Hrs
3	<b>Radiation: (Any One)</b> <ol style="list-style-type: none"> <li>1. Verification of Stefan Boltzmann Law</li> <li>2. Measurement of Emissivity of Grey surface</li> </ol>	2Hrs
4	<b>Transient Conduction:</b> <ol style="list-style-type: none"> <li>1. Unsteady state heat transfer in cylinder/rod/wall</li> </ol>	2Hrs
5	<b>Fins: (Any One)</b> <ol style="list-style-type: none"> <li>1. Determination of fin efficiency and fin effectiveness</li> <li>2. Comparison of fin performance of Various type of fins</li> </ol>	2Hrs
6.	<b>Boiling and Condensation: (Any One)</b> <ol style="list-style-type: none"> <li>1. Measurement of heat transfer coefficient in boiling process of water.</li> <li>2. Measurement of heat transfer coefficient in condensation of saturated steam.</li> </ol>	2Hrs
7	<b>Heat Exchangers: (Any One)</b> <ol style="list-style-type: none"> <li>1. Estimation of overall heat transfer coefficient and effectiveness of double pipe heat exchanger (parallel flow and Counter flow arrangement)</li> <li>2. Estimation of overall heat transfer coefficient and effectiveness of shell and tube heat exchanger (parallel flow and Counter flow arrangement)</li> <li>3. Estimation of overall heat transfer coefficient and effectiveness of plate type heat exchanger.</li> </ol>	2Hrs

**Assignments:** Assignment consisting of at least 3 numerical on each of the following topics

1. Steady state conduction
2. Fins and unsteady state conduction
3. Convection and dimensional analysis

4. Radiation
5. Heat Exchangers

Note: Preferably, the assignments shall be based on live problems. **Project Based Learning may be incorporated by judiciously reducing number of assignments.**

**Assessment:**

**Term work Mark distribution will be as follows:**

Laboratory work	15 marks
Assignments	05 marks
Attendance	05 marks

**End Semester Practical/Oral Examination:**

1. Pair of Internal and External Examiner should conduct practical/viva based on contents Distribution of marks for practical/viva examination shall be as follows:

Practical performance	15 marks
Oral	10 marks
2. Evaluation of practical examination to be done based on the experiment performed and the output of the experiment during practical examination
3. Students work along with evaluation report to be preserved till the next examination

Course Code	Course Name	Credits
<b>MEL504</b>	<b>Dynamics of Machinery*</b>	<b>1</b>

**Objectives:**

1. To acquaint with working principles and applications of gyroscope and governors
2. To acquaint with the principles of vibration measuring instruments
3. To study balancing of mechanical systems

**Outcomes:** Learner will be able to...

1. Plot and analyse governor characteristics
2. Analyse gyroscopic effect on laboratory model
3. Estimate natural frequency of mechanical systems
4. Analyse vibration response of mechanical systems
5. Determine damping coefficient of a system
6. Balance rotating mass

**Term Work:** (Comprises part a and b)

**a) List of Experiments: (Minimum Eight)**

Sr. No.	Title of Experiment	Laboratory Sessions
1	Experiments on Governors- Porter Governor, Hartnell Governor	2 hrs
2	Experiments on Gyroscope	2 hrs
3	Determine natural frequency of compound pendulum, equivalent simple pendulum system.	2 Hrs.
4	Determine natural frequency for longitudinal vibrations of helical springs, and springs in series and parallel	2 Hrs
5	Determine natural frequency and nodal points for single rotor and two-rotor vibratory system	2 Hrs
6	Experiment on whirling of shaft	2 Hrs
7	Determination of damping coefficient of any system/media	2 Hrs
8	Experimental balancing of single and multi-rotor system	2 Hrs
9	Measurement of vibration response of a system	2 Hrs
10	Vibration analysis of mechanical system using MATLAB/SCILAB/GNU Octave	2 Hrs

**b) Assignment:** Minimum two problems on each of the following topics:

1. Governors and Gyroscope
2. Static and dynamic force analysis
3. Vibration, isolation and control
4. Vibration measuring instruments
5. Rotor dynamics

**Project Based Learning may be incorporated by judiciously reducing number of assignments**

**Term Work**

The distribution of marks for term work shall be as follows:

- Laboratory work : 15 marks.
- Assignments : 05 marks.
- Attendance : 05 Marks.

Course Code	Course/Subject Name	Credits
<b>MEL 505</b>	<b>Manufacturing Sciences Lab</b>	<b>1</b>

**Objectives:**

1. To study conventional machining operations
2. To familiarise with CNC machining operation
3. To acquaint with Non Traditional machining operations

**Outcomes:** Learner will be able to...

1. Estimate machining time for simple and taper turning operations on lathe
2. Estimate machining time for threading/knurling operations on lathe
3. Estimate machining time for various machining operations on shaper
4. Perform NC, CNC and DNC machining operations
5. Write CNC program for different operations
6. Identify machining parameters for various Non Traditional machining operations

Sr No.	Details
<b>1</b>	Introduction to machining operations
<b>2</b>	Introduction to lathe machine (other than plain turning operation) and shaping machine
<b>3</b>	Machining and machining time estimation for taper turning
<b>4</b>	Machining and machining time estimation for thread cutting
<b>5</b>	Machining and machining time estimation for internal thread cutting
<b>6</b>	Machining and machining time estimation for knurling
<b>7</b>	Machining and machining time estimation for eccentric turning
<b>8</b>	Machining of hexagon and square in shaping machine
<b>9</b>	NC, CNC, DNC machining operations
<b>10</b>	CNC programming for Turning and Drilling operations
<b>11</b>	Different Non Traditional machining operations with process parameters

**Term Work:**

All the assignments mentioned above with relevant sketches.

Distribution of marks for Term work shall be as follows:

All the above listed assignments:	<b>20 marks</b>
Attendance:	<b>05 marks</b>

Subject Code	Subject Name	Credits
<b>MEL506</b>	<b>Business Communication &amp; Ethics</b>	<b>02</b>

**Objectives:**

1. To inculcate professional and ethical attitude at the workplace
2. To enhance effective communication and interpersonal skills
3. To build multidisciplinary approach towards all life tasks
4. To hone analytical and logical skills for problem-solving

**Outcomes:** Learner will be able to...

1. Design a technical document using precise language, suitable vocabulary and apt style.
2. Develop the life skills/ interpersonal skills to progress professionally by building stronger relationships.
3. Demonstrate awareness of contemporary issues knowledge of professional and ethical responsibilities.
4. Apply the traits of a suitable candidate for a job/higher education, upon being trained in the techniques of holding a group discussion, facing interviews and writing resume/SOP.
5. Deliver formal presentations effectively implementing the verbal and non-verbal skills

Module	Detailed Contents	Hrs.
<b>01</b>	<b>Report Writing</b>	<b>05</b>
1.1	Objectives of Report Writing	
1.2	Language and Style in a report	
1.3	Types : Informative and Interpretative (Analytical, Survey and Feasibility) and Formats of reports (Memo, Letter, Short and Long Report )	
<b>02</b>	<b>Technical Writing</b>	<b>03</b>
2.1	Technical Paper Writing (IEEE Format)	
2.2	Proposal Writing	
<b>03</b>	<b>Introduction to Interpersonal Skills</b>	<b>09</b>
3.1	Emotional Intelligence	
3.2	Leadership and Motivation	
3.3	Team Building	
3.4	Assertiveness	
3.5	Conflict Resolution and Negotiation Skills	
3.6	Time Management	
3.7	Decision Making	
<b>04</b>	<b>Meetings and Documentation</b>	<b>02</b>
4.1	Strategies for conducting effective meetings	
4.2	Notice, Agenda and Minutes of a meeting	
4.3	Business meeting etiquettes	
<b>05</b>	<b>Introduction to Corporate Ethics</b>	<b>02</b>
5.1	Professional and work ethics (responsible use of social media - Facebook, WA, Twitter etc.	
5.2	Introduction to Intellectual Property Rights	
5.4	Ethical codes of conduct in business and corporate activities (Personal ethics, conflicting values, choosing a moral response and making ethical decisions)	
<b>06</b>	<b>Employment Skills</b>	<b>07</b>
6.1	Group Discussion	

6.2	Resume Writing	
6.3	Interview Skills	
6.4	Presentation Skills	
6.5	Statement of Purpose	
		28

### Assessment:

#### List of Assignments

1. Report Writing (Theory)
2. Technical Proposal
3. Technical Paper Writing (Paraphrasing a published IEEE Technical Paper )
4. Interpersonal Skills (Group activities and Role plays)
5. Interpersonal Skills (Documentation in the form of soft copy or hard copy)
6. Meetings and Documentation (Notice, Agenda, Minutes of Mock Meetings)
7. Corporate ethics (Case studies, Role plays)
8. Writing Resume and Statement of Purpose

### Term Work

Term work shall consist of all assignments from the list.

The distribution of marks for term work shall be as follows:

Book Report	<b>10 marks</b>
Assignments:	<b>10 marks</b>
Project Report Presentation:	<b>15 marks</b>
Group Discussion:	<b>10 marks</b>
Attendance:	<b>05 marks</b>

### References:

1. Fred Luthans, "Organizational Behavior", Mc Graw Hill,
2. Lesiker and Petit, "Report Writing for Business ", Mc Graw Hill
3. R.Subramaniam, "Professional Ethics" Oxford University Press
4. Huckin and Olsen, "Technical Writing and Professional Communication", McGraw
5. Raman and Sharma, Fundamentals of Technical Communication, Oxford University Press
6. Hill Wallace and Masters, "Personal Development for Life and Work", Thomson Learning, 12<sup>th</sup> Edition
7. Heta Murphy, "*Effective Business Communication*" , Mc Graw Hill, edition
8. R.C Sharma and Krishna Mohan, "*Business Correspondence and Report Writing*",
9. Raman Sharma, *Communication Skills*, Oxford University Press
10. B N Ghosh, "*Managing Soft Skills for Personality Development*", Tata McGraw Hill Lehman,
11. Dufrene, Sinha, "*BCOM*", Cengage Learning, 2nd edition
12. Bell . Smith, "Management Communication" Wiley India Edition, 3rd edition.
13. Dr. K. Alex , "Soft Skills", S Chand and Company
14. Robbins Stephens P., "Organizational Behavior", Pearson Education
15. <https://grad.ucla.edu/asis/agep/advsopestem.pdf>

**Semester VI**

Course Code	Course Name	Teaching Scheme (Contact Hours)		Credits Assigned						
		Theory	Pract	Theory	Pract	Total				
MEC601	Metrology and Quality engineering	04	--	04	--	04				
MEC602	Machine Design I	04	--	04	--	04				
MEC603	Finite Element analysis	04	--	04	--	04				
MEC604	Refrigeration and Air Conditioning	04	--	04	--	04				
MEDLO 602X	Department Level Optional Course II	04	--	04	--	04				
MEL601	Metrology and Quality Engineering	--	02	--	01	01				
MEL602	Machine Design I	--	02	--	01	01				
MEL603	Finite Element Analysis	--	02	--	01	01				
MEL604	Refrigeration and Air Conditioning	--	02	--	01	01				
MEL605	Mechatronics Lab	--	02	--	01	01				
Total		20	10	20	05	25				
Course Code	Course Name	Examination Scheme								
		Theory					Exam Duration (Hrs)	Term Work	Pract/ Oral	Total
		Internal Assessment			End Sem Exam					
		Test1	Test 2	Avg						
MEC601	Metrology and Quality engineering	20	20	20	80	03	--	--	100	
MEC602	Machine Design I	20	20	20	80	03	--	--	100	
MEC603	Finite Element Analysis	20	20	20	80	03	--	--	100	
MEC604	Refrigeration and Air Conditioning	20	20	20	80	03	--	--	100	
MEDLO 602X	Department Level Optional Course II	20	20	20	80	03	--	--	100	
MEL601	Metrology and Quality engineering	--	--	--	--	--	25	25	50	
MEL602	Machine Design I	--	--	--	--	--	25	--	25	
MEL603	Finite Element analysis	--	--	--	--	--	25	25	50	
MEL604	Refrigeration and Air Conditioning	--	--	--	--	--	25	25	50	
MEL605	Mechatronics Lab	--	--	--	--	--	25	25	50	
Total				100	400		125	100	725	

Course Code	Department Level Optional Course II
MEDLO6021	Mechatronics
MEDLO6022	Robotics
MEDLO6023	Industrial Automation



Course Code	Course/Subject Name	Credits
<b>MEC 601</b>	<b>Metrology and Quality Engineering</b>	<b>4</b>

### Objectives:

1. To acquaint with measuring equipment used for linear and angular measurements.
2. To familiarize with different classes of measuring instruments and scope of measurement in industry and research
3. To acquaint with operations of precision measurement, instrument/equipment for measurement
4. To inculcate the fundamentals of quality concepts and statistics in metrology

### Outcomes: Learner will be able to...

1. Demonstrate inspection methods and different gauges
2. Illustrate working principle of measuring instruments and calibration methodology
3. Illustrate basic concepts and statistical methods in quality control
4. Demonstrate characteristics of screw threads, gear profile, and tool profile
5. Illustrate the different sampling techniques in quality control
6. Illustrate different nondestructive techniques used for quality evaluation

Module	Details	Hours
1	<b>1.1 Introduction to Metrology:</b> Fundamental Definitions, Types of Standards, Precision and Accuracy, Measurement Errors, linear measurements by Vernier calliper, micrometer, slip gauges, Angular Measurement: Universal bevel protractor, clinometers, sine bar, angle gauges case studies on Industrial and Research Applications and Scope <b>1.2 Introduction to Nano-Metrology</b>	06
2	<b>1.3 Design of Gauges :</b> Limits, Fits, Tolerances, Types of Gauges, Taylor's Principle of Limit Gauges, IS 919 for design of gauges <b>1.4 Comparators :</b> Definition, Classification, Working principle of Mechanical, Opto-mechanical, Pneumatic and Electrical/Electronic comparators with advantages, limitations and uses <b>1.5 Surface Texture measurement:</b> Surface roughness, Waviness, Roughness Parameter Ra, Rz, RMS etc., working of Tomlinson surface meter, Taly-surf surface roughness tester, Surface roughness symbols <b>1.6 Flatness Test measurement by Interference principle:</b> Concept of Flatness, Interferometer principle for measurement, Optical Flats – study of Surface textures under monochromatic light source, fingertip test technique	14
3	<b>3.1 Screw Thread Measurement :</b> Screw threads Terminology, screw thread errors, Effective diameter measurement of screw thread by Floating Carriage micrometer <b>3.2 Gear Measurement :</b> Gear Terminology, Gear errors, Measurement by Parkinson Gear tester and Gear tooth Vernier Calliper <b>3.3 Special Measuring Instruments :</b> Measurement by Tool Maker's Microscope, Optical Profile Projector, CMM and Autocollimator	12

4	<b>4.1 Quality Engineering</b> Introduction to Quality, Classification of Quality Tools, Quality of Design, Quality of Conformance, Compromise between Quality and Cost, Introduction to Six Sigma <b>4.2 SQC &amp; SQC tools</b> Statistics in Quality control, Variables and Attributes data, Process Capability, Control charts for variables and for attribute data( $\bar{X}$ and R-Chart, p-chart np-chart, c-chart, U-chart), Applications of SQC in engineering – case studies	08
5	<b>5.1 Sampling Techniques</b> Advantages of Sampling Inspection, operating characteristic (OC) curve. Choosing OC curve for appropriate sampling plan, acceptance sampling <b>5.2 Role of computers in metrology</b>	04
6	<b>6.1 Non-destructive Testing</b> Visual, Dye Penetrant, Magnetic Particle, X ray Radiography, Ultrasonic Testing, Eddy Current testing methods.	04

### **Assessment:**

#### **Internal Assessment for 20 marks:**

##### **Consisting Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

### **References**

1. Engineering Metrology, K.J. Hume, Kalyani Publications
2. Mechanical Measurements and Metrology by RKJain, Khanna Publishers
3. A text book of Engineering Metrology by IC Gupta, Dhanpat Rai Publications
4. Metrology and Measurement by Anand, Bewoor and Vinay Kulkarni, McGraw Hill
5. Engineering Metrology and Measurement by N V Raghavendra and Krishnamurthy, Oxford University Press
6. Engineering Metrology and Measurements, Bentley, Pearson Education
7. Statistical Quality Control by AL Grant, McGraw Hill, New York
8. Statistical Quality Control by R C Gupta, Khanna Publishers
9. Juran on Planning for Quality, Juran J M, The Free Press, 1988.
10. Statistical Quality Control by M Mahajan, Dhanpat Rai and Sons

Course Code	Course Name	Credits
<b>MEC602</b>	<b>MACHINE DESIGN – I*</b>	<b>4</b>

### Objective:

1. To study basic principles of machine design
2. To acquaint with the concepts of design based on strength & rigidity
3. To familiarize with use of design data books & various codes of practice
4. To make conversant with preparation of working drawings based on designs

### Outcomes: Learner will be able to...

1. Demonstrate understanding of various design considerations
2. Illustrate basic principles of machine design
3. Design machine elements for static as well as dynamic loading
4. Design machine elements on the basis of strength/ rigidity concepts
5. Use design data books in designing various components
6. Acquire skill in preparing production drawings pertaining to various designs

Modules	Details	Hrs.
<b>1</b>	Mechanical Engineering Design, Design methods, Aesthetic and Ergonomics consideration in design, Material properties and their uses in design, Manufacturing consideration in design, Design consideration of casting and forging, Basic principle of Machine Design, Modes of failures, Factor of safety, Design stresses, Theories of failures (Selection in the process of designing), Standards, I.S. Codes, Preferred Series and Numbers	<b>06</b>
<b>2</b>	<b>Curved Beams:</b> Assumptions made in the analysis of curved beams, Design of curved beams: Bending stresses in curved beams, such as crane hook, C-frame, etc. <b>Thick Cylinders:</b> Design of thick cylinders subjected to an internal pressure using Lamé's equation	<b>06</b>
<b>3</b>	<b>Design against static loads:</b> Cotter joint, Knuckle joint, Turn buckle, Bolted and welded joints under eccentric loading; Power Screw – screw presses, C-clamps along with the Frame, Screw Jack	<b>12</b>
<b>4</b>	<b>Design against fluctuating loads:</b> variables stresses, reversed, repeated, fluctuating stresses. Fatigue failure: static and fatigue stress concentration factors, Endurance limit- estimation of endurance limit, Design for finite and infinite life, Soderberg and Goodman design criteria, Fatigue design under combined stresses	<b>06</b>
<b>5</b>	<b>Design of Shaft:</b> power transmitting, power distribution shafts, Module (excluding crank shaft) under static and fatigue criteria <b>Keys:</b> Types of Keys and their selection based on shafting condition <b>Couplings:</b> Classification of coupling, Design of Flange couplings, Bush pin type flexible couplings	<b>11</b>
<b>6</b>	<b>Design of Springs:</b> Helical compression, Tension Springs under Static and Variable loads, Leaf springs	<b>07</b>

### Assessment:

#### Internal Assessment for 20 marks:

#### Consisting Two Compulsory Class Tests

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

**End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

**References:**

1. Design of Machine Elements - V.B. Banadari, Tata McGraw Hill Publication
2. Design of Machine Elements - Sharma, Purohil. Prentice Hall India Publication
3. Machine Design -An Integrated Approach - Robert L. Norton, Pearson Education
4. Machine Design by Pandya & Shah, Charotar Publishing
5. Mechanical Engineering Design by J.E.Shigley, McGraw Hill
6. Recommended Data Books - PSG
7. Machine Design by Reshetov, Mir Publication
8. Machine Design by Black Adams, McGraw Hill
9. Fundamentals of Machine Elements by Hawrock, Jacobson McGraw Hill
10. Machine Design by R.C.Patel, Pandya, Sikh, Vol-I & II C. Jamnadas & Co
11. Design of Machine Elements by V.M.Faires
12. Design of Machine Elements by Spotts

Course Code	Course Name	Credits
<b>MEC603</b>	<b>Finite Element Analysis</b>	<b>4</b>

### Objectives:

1. To familiarise with concepts of FEM
2. To study the applicability of FEM to engineering problems
3. To acquaint with application of numerical techniques for solving problems

### Outcomes: Learner will be able to...

1. Solve differential equations using weighted residual methods
2. Develop the finite element equations to model engineering problems governed by second order differential equations
3. Apply the basic finite element formulation techniques to solve engineering problems by using one dimensional elements
4. Apply the basic finite element formulation techniques to solve engineering problems by using two dimensional elements
5. Apply the basic finite element formulation techniques to find natural frequency of single degree of vibration system
6. Use commercial FEA software, to solve problems related to mechanical engineering

Module	Details	Hrs.
<b>01</b>	<b>Introduction:</b> 1.1 Introductory Concepts: Introduction to FEM, Historical Background, General FEM procedure, Applications of FEM in various fields Advantages and disadvantages of FEM 1.2 Mathematical Modelling of field problems in engineering, Governing equations, Differential equations in different fields 1.3 Approximate solution of differential equations, Weighted residual techniques, Boundary value problems	<b>08</b>
<b>02</b>	<b>FEA Procedure:</b> 2.1 Discrete and Continuous Models, Weighted Residual Methods - Ritz Technique- Basic Concepts of the, Finite Element Method 2.2 Definitions of various terms used in FEM like element, order of the element, internal and external node/s, degree of freedom, primary and secondary variables, boundary conditions. 2.3 Minimization of a functional, Principle of minimum total potential, Piecewise Rayleigh-Ritz method, Formulation of 'stiffness matrix', transformation and assembly concepts	<b>08</b>
<b>03</b>	<b>One Dimensional Problems:</b> 3.1 One dimensional second order equations - discretization-element types - linear and higher order elements -derivation of shape functions and stiffness matrices and force vectors 3.2 Assembly of Matrices- solution of problems in one dimensional structural analysis, heat transfer and fluid flow (stepped and taper bars, fluid network, spring-Cart Systems) 3.3 Analysis of Plane trusses, Analysis of Beams 3.4 Solution of one dimensional structural and thermal problems using FE Software, Selection of suitable element type, modelling, meshing, boundary condition, convergence of solution, result analysis, case studies	<b>10</b>
<b>04</b>	<b>Two Dimensional Finite Element Formulations:</b> 4.1 Introduction, three node triangular element, four node rectangular element, four node quadrilateral element, eight node quadrilateral element 4.2 Natural coordinates and coordinates transformations: serendipity and Lagrange's methods for deriving shape functions for triangular and quadrilateral element 4.3 Sub parametric, Isoparametric, super parametric elements, Compatibility, Patch test, Convergence criterion, sources of errors	<b>08</b>

<b>05</b>	<b>Two Dimensional Vector Variable Problems:</b> 5.1 Equations of elasticity - Plane stress, plane strain and axisymmetric problems 5.2 Jacobian matrix, stress analysis of CST and four node Quadratic element	<b>08</b>
<b>06</b>	<b>Finite Element Formulation of Dynamics and Numerical Techniques:</b> 6.1 Applications to free vibration problems of rod and beam, Lumped and consistent mass matrices 6.2 Solutions techniques to Dynamic problems, longitudinal vibration frequencies and mode shapes, Fourth order beam equation, transverse deflections and natural frequencies of beams	<b>06</b>

### **Assessment:**

#### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

#### **References:**

1. Text book of Finite Element Analysis by Seshu P, Prentice Hall of India
2. Finite Element Method by JNReddy, TMH
3. 'Introduction to Finite Elements in Engineering, Chandrupatla and Belegundu, Pearson Education
4. Finite Element Methods by R Dhanraj and K Prabhakaran Nair, Oxford University Press
5. A first course in Finite Element Method by Logan D L, Thomson Asia PvtLtd
6. 'Concepts and Applications of Finite Element Analysis by Cook R D, Malkus D S, Plesha ME, John-Wiley Sons
7. The Finite Element Method in Engineering by SSRao, Butter WorthHeinemann
8. Fundamental Finite Element Analysis and Application with Mathematica and MATLAB Computations by M. Asghar Bhatti, Wiley India Pvt. Ltd.

Course Code	Course/Subject Name	Credits
<b>MEC604</b>	<b>Refrigeration and Air Conditioning</b>	<b>4</b>

### Objectives

1. To study working and operating principles of Air Refrigeration, Vapour Compression and Vapour Absorption system
2. To study components of refrigeration and air conditioning systems
3. To study controls and applications of refrigeration and air conditioning

### Outcomes: Learner will be able to...

1. Demonstrate fundamental principles of refrigeration and air conditioning
2. Identify and locate various important components of the refrigeration and air conditioning system
3. Illustrate various refrigeration and air conditioning processes using psychometric chart
4. Design Air Conditioning system using cooling load calculations.
5. Estimate air conditioning system parameters
6. Demonstrate understanding of duct design concepts

Module	Detailed Contents	Hrs.
01	<b>Introduction to Refrigeration:</b> Methods of refrigeration, First and Second Law applied to refrigerating machines, Carnot refrigerator, Carnot heat pump, unit of refrigeration, Co-efficient of Performance, Energy Efficiency Ratio (EER), and BEE star rating Air refrigeration systems: Bell Coleman cycle, applications Aircraft air refrigeration systems: Need for aircraft refrigeration, Simple, Bootstrap including evaporative cooling, Reduced ambient, Regenerative air cooling system, Comparison of these systems based on DART rating.	08
02	<b>Vapour Compression Refrigeration System:</b> Simple vapour compression cycle, Effect of liquid sub cooling & superheating, effect of evaporator and condenser pressures, methods of subcooling, use of P-h charts, Actual VCR cycle, Use of P-h Charts, Comparison between air-cooled and water-cooled condenser based air conditioning systems, Types of condensers, evaporators, expansion devices and Compressors <b>Cooling tower:</b> Types of cooling towers, tower approach, tower range, tower efficiency, tower losses, tower maintenance <b>Refrigerants:</b> Desirable properties of refrigerants, ASHRAE numbering system for refrigerants. Thermodynamic, Chemical and Physical properties, Secondary refrigerants, ODP and GWP, Montreal protocol and India's commitment, Recent substitutes for refrigerants	12
03	<b>Other Refrigeration Systems:</b> Vapour Absorption Refrigeration, Importance of VAR system, COP of ideal VAR system, Ammonia-water VAR system, Lithium Bromide – Water VAR system, Single and double effect, Electrolux refrigeration system, <b>Non-Conventional Refrigeration Systems:</b> Thermoelectric Refrigeration, Thermo-acoustic Refrigeration, Vortex Tube Refrigeration	06
04	<b>Psychrometry:</b> Need for air conditioning, Principle of psychrometry, Psychrometric properties, chart and processes, air washers, requirements of comfort air conditioning, summer and Winter Air conditioning	05
05	<b>Design of Air Conditioning Systems:</b> Different Heat sources,- Adiabatic mixing of two air streams, Bypass factor, sensible heat factor, RSHF, GSHF, ERSHF, Room apparatus dew point and coil apparatus dew point, Ventilation and infiltration, Inside and Outside Design condition, Cooling Load estimation, Introduction to Unitary Products viz. Room/Split and Packaged Air Conditioners, Introduction to recent developments viz. Variable Refrigerant Flow systems, VAV control systems, Inverter Units. Human Comfort, Thermal exchange of body with environment, Effective temperature, Comfort chart, Comfort zone, Indoor Air Quality, Green Buildings	12

	<b>Duct Design</b> Friction chart for circular ducts, Equivalent diameter of a circular duct for rectangular ducts, Static pressure regain and equal pressure drop methods of duct design, Factors considered in air distribution system, Air distribution systems for cooling and heating	
06	<b>Controls and Applications:</b> Controls – LP/HP cutoff, Thermostats, Humidistats, Interlocking control, Electronic Controllers Applications Refrigeration & A/C Ice plant – food storage plants – dairy and food processing plants, Food preservation ,Freeze Drying, A/c in textile ,printing pharmaceutical industry and Hospitals , Liquefaction of LNG, Liquefaction of gases (cryogenics), Deep sea water air-conditioning	05

### **Assessment:**

#### **Internal Assessment for 20 marks:**

##### **Consisting Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

### **References**

- 1 Refrigeration and air-conditioning – C P Arora, TMH
- 2 Principles of refrigeration – R J Dossat, Willey Eastern Publication
- 3 Refrigeration and air-conditioning – W F Stoeker and J W Jones, TMH
- 4 Modern Air-conditioning practice – C P Arora, TMH
- 5 Refrigeration and air-conditioning- Manohar Prasad, New Age Int (P) Ltd
- 6 Basic Refrigeration and air-conditioning- P.Ananthanarayana, TMH
- 7 ASHRAE Handbook of Fundamentals
- 8 ASHRAE Handbook of Systems
- 9 ASHRAE Handbook of Equipment
- 10 ISHRAE Air Conditioning Handbook
- 11 ISHRAE Refrigeration Handbook



Course Code	Course Name	Credits
<b>MEDLO6021</b>	<b>Mechatronics</b>	<b>4</b>

### Objectives

1. To study key elements of Mechatronics system and its integration
2. To familiarise concepts of sensors characterization and its interfacing with microcontrollers
3. To acquaint with concepts of actuators and its interfacing with microcontrollers
4. To study continuous control logics i.e. P, PI, PD and PID
5. To study discrete control logics in PLC systems and its industrial applications

### Outcomes: Learner will be able to...

1. Identify the suitable sensor and actuator for a mechatronics system
2. Select suitable logic controls
3. Analyse continuous control logics for standard input conditions
4. Develop ladder logic programming
5. Design hydraulic/pneumatic circuits
6. Design a mechatronic system

Module	Detailed Contents	Hrs.
<b>1</b>	<b>Introduction of Mechatronics and its block diagram representation</b> Key elements of mechatronics, Applications of Mechatronics domestic, industrial etc. Representation of mechatronic system in block diagram and concept of transfer function for each element of mechatronic system, Reduction methods and its numerical treatment for represented block diagram	08
<b>2</b>	<b>Selection of Sensors &amp; Actuators</b> Sensors: Criteria for selection of sensors based on requirements, principle of measurement, sensing method, performance chart etc. (Displacement, temperature, acceleration, force/pressure) based on static and dynamic characteristics. Actuators: Selection of actuators based on principle of operation, performance characteristics, maximum loading conditions, safety etc. Principle and selection of mechano-electrical actuators (1) DC motors (2) Stepper Motors (3) Solenoid Actuators (4) Servo Motors (5) BLDC	08
<b>3</b>	<b>Data Acquisition, Signal Conditioning &amp; Microcontroller System Theory:</b> Concept of Bit accuracy/width and Sampling speed, sampling theorem, aliasing, Nyquist criteria, ADC (Analog to Digital Convertor) Successive approximation method and sample and hold circuitry, DAC (Digital to Analog Convertor) R-2R circuit and DAC resolution Signal Filters: Low pass, High Pass and Band Pass with circuit diagrams for simple cases	08
<b>4</b>	<b>Pneumatics and hydraulics:</b> Hydraulic and pneumatic devices: Different types of valves, Actuators and auxiliary elements in Pneumatics and hydraulics, their applications and use of their ISO symbols, Synthesis and design of circuits (up to 2 cylinders)–pneumatic, electro- pneumatics and hydraulics, electro-hydraulics	08
<b>5</b>	<b>Control System</b> Control system design and analysis by Root Locus Method, Control system Design by Frequency response method, stability margin, Nyquist diagram, Bode diagram P, I and D control actions, P, PI, PD and PID control systems, Transient response:- Percentage overshoot, Rise time, Delay time, Steady state error, PID tuning (manual), Ziegler Method	08
<b>6</b>	<b>Discrete Control System PLC (Programming Logic Control) Theory:</b> Introduction to PLC, Architecture, Ladder Logic programming for different types of logic gates, Latching, Timers, Counter, Practical Examples of Ladder Programming	08

## **Assessment:**

### **Internal Assessment for 20 marks:**

Consisting **Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

## **References**

1. Mechatronics, Kenji Uchino and Jayne R. Giniewicz, publication: Marcel Dekker, Inc
2. Applied Mechatronics- A. Smaili and F. Mrad, OXFORD university press
3. Mechatronics System Design , Shetty and Kolk, Cengage Learning, India Edition
4. Introduction to Mechatronics and Measurement Systems, Alciatore and HistanTata McGraw-Hill
5. Mechatronics, Necsulescu, Pearson education
6. Mechatronics - Electromechanics and Control Mechanics , Mill Springer-Verlag
7. Mechatronics - Electronic Control Systems in Mechanical Engineering , Bolton Pearson education
8. Mechatronics - Electronics in products and processes , Bradley, et al. Chapman and Hall
9. Mechatronics - Mechanical System Interfacing , Auslander and Kempf, Prentice Hall
10. Introduction to Mechatronics, AppuKuttan K.K., OXFORD Higher Education
11. Pneumatic Circuits and Low Cost Automation by Fawcett JR
12. The Art of Electronics, Horowitz and Hill Cambridge, University Press
13. Electromechanical Design Handbook , Walsh, McGraw-Hill
14. Electro-mechanical Engineering - An Integrated Approach , Fraser and Milne
15. Handbook of Electromechanical Product Design , Hurricks Longman, John Wiley, Addison Wesley
16. Principles and Applications of Electrical Engineering , Rizzoni, Irwin Publishing
17. Understanding Electro-Mechanical Engineering - An Introduction to Mechatronics , KammIEEE
18. Modeling and control of Dynamic Systems, Macia and Thaler, Cengage Learning, India Edition
19. Mechatronics, A. Smaili, F. Mrad, OXFORD Higher Education.
20. Pneumatic and Hydraulic Control Systems: Aizerman. M.A.
21. Industrial Hydraulics: Pippenger
22. Vickers Manual on Hydraulics
23. Computer Numerical Control of Machine Tools: Thyer. G.R.
24. Pneumatic Applications: Deppert Warner & Stoll Kurt
25. Mechanization by Pneumatic Control: Vol. 1 & 2 Deppert Warner & Stoll kurt
26. Hydraulics and Pneumatics for Production: Stewart
27. Hydraulic Valves and Controls: Pippenger
28. Fundamentals of pneumatics: Festo series
29. Automatic Control Engineering: Francis. H. Raven.
30. Mechatronics, NitaigourMahalik, Tata McGraw-Hill
31. Mechatronics, HMT
32. System Identification: Theory for the User (2nd Edition) , Lennart Ljung
33. Design with Microprocessors for Mechanical Engineers, StifflerMcGraw-Hill

Course Code	Course/Subject Name	Credits
<b>MEDLO6022</b>	<b>Robotics</b>	<b>04</b>

### Objectives:

1. To study the basics of robotics and its control
2. To study various design principles of robotics through kinematic analysis, workspace analysis, and trajectory planning
3. To study applications of robots in industrial inspection and material handling
4. To study the role of a robot as a humanoid

### Outcomes: Learner will be able to...

1. Demonstrate the basic functioning of a robot
2. Identify various components of robots
3. Carryout kinematic analysis, workspace analysis, and trajectory planning for a robot
4. Identify suitable sensors/actuators for robot
5. Select an appropriate robot for given industrial inspection and material handling systems.
6. Illustrate various aspects of a robot as a humanoid

Module	Details	Hrs.
01	<b>Introduction</b> Definition of robot, Evolution of robots, Laws of robots, International Robotic Standards, Types of robots, Selection of robots, Robot Classifications, Degrees of freedom, Robot configuration, Accuracy and repeatability, Specification of a robot, Robot feedback controls: Point to point control and Continuous path control, Control system for robot joint, Adaptive control, Actuators and sensors, Drives and transmission systems, End effectors, Applications of robots	08
02	<b>Kinematics of Robots</b> <b>Direct:</b> Link coordinates D-H Representation, The ARM equation, Direct kinematic analysis for Four axis, SCARA Robot and three, five, and six axis Articulated Robots. <b>Inverse:</b> The inverse kinematics problem, General properties of solutions, Tool configuration, Inverse kinematics of four axis SCARA robot and three and five axis Articulated robot. <b>Mobile Robot Kinematics</b> Introduction, Kinematic models and constraints, Representing robot position, Forward kinematic models, Wheel kinematic constraints, Robot kinematic constraints, Mobile robot maneuverability, Degree of mobility, Degree of steerability, Mobile robot workspace, Degree of freedom, Holonomic robots, Path and trajectory considerations, Motion control, Open loop control, Feedback control.	10
03	<b>Workspace Analysis and Trajectory Planning</b> Workspace Analysis, work envelope of a Four axis SCARA robot and five axis articulated robot workspace fixtures, the pick and place operations, Joint space technique - Continuous path motion, Interpolated motion, Straight line motion and Cartesian space technique in trajectory planning.	10
04	<b>Sensors &amp; Actuators</b> Sensors: Selection of sensors (Displacement, temperature, acceleration ,force/pressure) based on static and dynamic charecterstics, Interfacing: Concept of interfacing, bit accuracy and sampling speed, amplifying electronics, and microcontroller Actuators: Principle and selection of mechano-electrical actuators (1) DC motors (2) Stepper Motors (3) Solenoid Actuators (4) Servo Motors (5) BLDC	08

05	<b>Robots for Inspection and Material Handling</b> Robotic vision systems, Image representation, Object recognition and categorization, Depth measurement, Image data compression, Visual inspection, Software considerations Concepts of material handling, Principles and considerations in material handling systems design, Conventional material handling systems - Industrial trucks, Monorails, Rail guided vehicles, Conveyor systems, Cranes and Hoists, Advanced material handling systems, Automated guided vehicle systems, Automated storage and retrieval systems, Bar code technology, Radio frequency identification technology	08
06	<b>Humanoids</b> Wheeled and legged, Legged locomotion and balance, Arm movement, Gaze and auditory orientation control, Facial expression, Hands and manipulation, Sound and speech generation, Motion capture/Learning from demonstration, Human activity recognition using vision, touch, and sound, Vision, Tactile Sensing, Models of emotion and motivation, Performance, Interaction, Safety and robustness, Applications, Case studies	08

### **Assessment:**

#### **Internal Assessment for 20 marks:**

##### **Consisting Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

### **References**

1. Yoram Korean, "Robotics for engineers", McGraw Hill Co.
2. M.P. Groover, M. Weiss, R.N. Nagel, and N.G. Odrey, "Industrial Robotics Technology programming and Applications", McGraw-Hill,
3. Robotics: Fundamental Concepts and Analysis by Ashitava Ghosal, Oxford University Press
4. R.K. Mittal and I.J. Nagrath, "Robotics and Control", TMH Publications
5. Robert J. Schilling, "Fundamentals of Robotics Analysis and Control", PHI Learning
6. Bijay K. Ghosh, Ning Xi, T.J. Tarn, Control in Robotics and Automation Sensor – Based integration, Academic Press
7. K.S.Fu, R.C.Gonzalez, and C.S.G.Lee, "Robotics Control Sensing, Vision and Intelligence", McGraw hill Book co.
8. Hartenberg and Denavit, "Kinematics and Synthesis of linkages", McGraw Hill Book Co.
9. A.S. Hall, "Kinematics and Linkage Design", Prentice Hall
10. J.Hirchhorn, "Kinematics and Dynamics of Machinery", McGraw Hill Book Company

11. P.A. Janaki Raman, “Robotics and Image Processing An Introduction”, Tata McGraw Hill Publishing company Ltd.
12. Richard D Klafter, Thomas A Chmielewski, and Michael Negin, “Robotics Engineering – An Integrated Approach”, Eastern Economy Edition, Prentice Hall of India P Ltd.
13. Roland Siegwart, Illah Reza Nourbakhsh, and Davide Scaramuzza, “Introduction to Autonomous Mobile Robots”, Bradford Company Scituate, USA
14. Alonzo Kelly, Karl Iagnemma, and Andrew Howard, “Field and Service Robotics”, Springer
15. Riadh Siaer, “The future of Humanoid Robots- Research and applications”, Intech Publications

Course Code	Course Name	Credits
<b>MEDLO6023</b>	<b>Industrial Automation</b>	<b>4</b>

**Objectives:**

1. To study the need for the automation, its advantages and limitations
2. To study the basic functional elements of automation
3. To familiarise with the levels of automation and strategies of automation
4. To acquaint with control of mechanical operations involving pneumatic, electric, hydraulic and electronic systems

**Outcomes:** Learner will be able to...

1. Demonstrate basics of industrial automation
2. Identify various types of automation
3. Demonstrate use of automated controls using pneumatic and hydraulic systems.
4. Illustrate the control systems in automated system.
5. Demonstrate applicability of PLC in process industry
6. Design electro-pneumatic circuits

Module	Detailed Contents	Hrs.
<b>01</b>	<b>Introduction to Automation:</b> Definition and fundamentals of automation, reasons for Automating, basic elements of an automated system: Power, Program and control system <b>Advanced automation functions:</b> safety, maintenance & repair diagnosis, error detection and recovery <b>Levels of automation</b> <b>Automation principles and strategies:</b> USA principle, ten strategies of automation and production system, automation migration strategy	06
<b>02</b>	<b>Mechanization and Automation:</b> Mechanization and automation, product cycle, hard Vs flexible automation, Capital- intensive Vs low cost automation Types of systems-mechanical, electrical, hydraulic, pneumatic and hybrid systems Automation using CAMS, Geneva mechanisms, gears etc. Assembly line Automation: automated assembly systems, transfer systems, vibratory bowl feeders, non-vibratory feeders, part orienting, feed track, part placing & part escapement systems Introduction to Material storage/ handling and transport systems, and its automation using AS/RS, AGVS and conveyors etc.	08
<b>03</b>	<b>Pneumatics and hydraulics:</b> Hydraulic and pneumatic devices-Different types of valves , Actuators and auxiliary elements in Pneumatics & hydraulics , their applications and use of their ISO symbols Synthesis and design of circuits (up to 3 cylinders)–pneumatic, electro pneumatics and hydraulics Design of Electro-Pneumatic Circuits using single solenoid and double solenoid valves; with and without grouping	14
<b>04</b>	Sensors & Actuators Sensors: Selection of sensors ( Displacement, temperature, acceleration, force /pressure) based on static and dynamic characteristics Interfacing: Concept of interfacing, bit accuracy and sampling speed, amplifying electronics, and microcontroller Actuators: Principle and selection of mechano-electrical actuators (1) DC motors (2) Stepper Motors (3) Solenoid Actuators (4) Servo Motors (5) BLDC	06

05	<b>Industrial control systems:</b> Process industries versus discrete manufacturing industries, Continuous versus discrete control, Computer process control, Forms of computer process control Discrete control using PLC- discrete process control, Programmable logic controller, its architecture, ladder logic, Ladder Logic Programming for different types of logic gates, Latching, Timers, Counter, Practical Examples of Ladder Programming	10
06	<b>Robots and their applications:</b> Introduction to robots, Types, Classifications, Selection of robots, Robot Degrees of freedom, Robot configuration, Accuracy and repeatability, Specification of a robot, Robot feedback controls: Point to point control and Continuous path control, Control system for robot joint, Adaptive control, Drives and transmission systems, End effectors, Industrial robot applications of robots	08

### **Assessment:**

#### **Internal Assessment for 20 marks:**

##### **Consisting Two Compulsory Class Tests**

First test based on approximately 40% of contents and second test based on remaining contents (approximately 40% but excluding contents covered in Test I)

#### **End Semester Examination:**

Weightage of each module in end semester examination will be proportional to number of respective lecture hours mentioned in the curriculum.

1. Question paper will comprise of total **six questions, each carrying 20 marks**
2. **Question 1** will be **compulsory** and should **cover maximum contents of the curriculum**
3. **Remaining questions will be mixed in nature** (for example if Q.2 has part (a) from module 3 then part (b) will be from any module other than module 3)
4. Only **Four questions need to be solved**

### **Reference Books:**

1. M.P. Groover "Automation, Production Systems and Computer Integrated Manufacturing", Pearson Education, New Delhi
2. Jeffrey Boothroyd, Peter Dewhurst and Winston A. Knight, "Product Design for manufacture and Assembly", CRC Press
3. M.P. Groover, M. Weiss, R.N. Nagel, and N.G. Odrey, "Industrial Robotics Technology programming and Applications", McGraw-Hill,
4. Yoram Koren, "Robotics for engineers", McGraw Hill Co
5. John W Webb and Reis, Ronald A., "Programmable Logic Controllers: Principles & Applications", Prentice Hall.
6. Frank Petruzella, "Programmable Logic Controllers", McGraw-Hill Education; 4 edition
7. Industrial Hydraulics: Pippenger
8. Mechatronics - Mechanical System Interfacing, Auslander and Kempf, Prentice Hall
9. Pneumatic Circuits and Low Cost Automation: by Fawcett J.R.
10. Fundamentals of pneumatics: Festo series

Course Code	Course/Subject Name	Credits
<b>MEL601</b>	<b>Metrology and Quality Engineering</b>	<b>1</b>

### Objectives:

1. To familiarise with working of gauges
2. To acquaint with gear parameter measurement
3. To acquaint with operations of precision measurement, instrument/equipment for measurement
4. To inculcate the fundamentals of quality concepts and statistics in metrology

### Outcomes: Learner will be able to...

1. Measure linear and angular dimensions
2. Measure surface roughness
3. Measure various parameters of gear tooth profile
4. Use optical profile projector for measurement
5. Use various instruments for measurement of screw threads
6. Measure flatness by Autocollimator / Interferometry method

Six Experiments need to be performed on the below mentioned topics:

Sr. No.	Topic
1	Vernier Calliper, Micrometer and Bevel Protractor for linear and angular measurement
2	Surface measurement by Surface roughness tester
3	Gear measurement – Gear tooth Vernier calliper / Parkinson gear tester
4	Screw Thread Measurement – screw thread Micrometer, Floating carriage micrometer /bench micrometer
5	Optical profile projector for miniature linear / angular measurements of screw / gear or components
6	Tool maker's microscope for linear / angular measurement of single point tools
7	Comparator – Mechanical / Pneumatic type
8	Flatness measurement by Autocollimator / Interferometry method
9	QC charts for 50 sample readings of OD / ID of specimen and printouts

### Term-Work

Consists of minimum six experiments from the above list and presented with Aim, Apparatus/equipment's, and Introduction, Working principle, Diagram, method, observation table, Analysis, Results and conclusion/inferences.

Also, minimum 5 assignments to help smooth conducting of laboratory exercises and one case study relevant to contents

### Project Based Learning may be incorporated by judiciously reducing number of assignments

Distribution of marks for term work shall be as follows:

Laboratory work:	<b>15 marks</b>
Assignments:	<b>05 marks</b>
Attendance:	<b>05 marks</b>

### End Semester Practical/Oral examination

1. Pair of Internal and External Examiner should conduct practical/viva based on contents
2. Distribution of marks for practical/viva examination shall be as follows:
  - a) Practical performance .....**15 marks**
  - b) Oral .....**10 marks**
3. Evaluation of practical examination to be done based on the experiment performed and the output of the experiments during practical examination.
4. Students work along with evaluation report to be preserved till the next examination



Course Code	Course Name	Credits
<b>MEL602</b>	<b>Machine Design –I *</b>	<b>1</b>

**Objectives:**

1. To study the basic design principles
2. To familiarize with use of design data books & various codes of practice
3. To make conversant with preparation of working drawings based on designs

**Outcomes:** Learner will be able to...

1. Design shaft under various conditions
2. Design Knuckle Joint / cotter joint
3. Design Screw Jack/C-clamp along with frame
4. Design Flexible flange couplings/ Leaf spring
5. Convert design dimensions into working/manufacturing drawing
6. Use design data book/standard codes to standardise the designed dimensions

**Term Work:** (Comprises a & b)

**a) Term work** - Shall consist of (minimum 3) design exercises from the list which may include computer aided drawing on **A3 size sheets**.

- 1) Knuckle Joint / cotter joint
- 2) Screw Jack
- 3) Flexible flange couplings
- 4) Leaf springs
- 5) C-clamps along with the Frame

**b) Assignment:** Design exercises in the form of design calculations with sketches and/ or drawings on following machine elements.

- 1) Bolted and welded joints
- 2) Combined stresses problem using theory of failure.
- 3) Shaft design (solid and hollow shaft)
- 4) Design against fluctuating loads (finite and infinite life)

The distribution of marks for term work shall be as follows:

- Part - a : 15 marks.
- Part--b : 05 marks.
- Attendance: 05 Marks.

Course Code	Course Name	Credits
<b>MEL603</b>	<b>Finite Element Analysis</b>	<b>1</b>

**Objectives:**

1. To familiarise FEA concept for practical implementation
2. To acquaint with FEA application software

**Outcomes:** Learner will be able to...

1. Select appropriate element for given problem
2. Select suitable meshing and perform convergence test
3. Select appropriate solver for given problem
4. Interpret the result
5. Apply basic aspects of FEA to solve engineering problems
6. Validate FEA solution

**Term Work:** (Comprises a and b)

**a) List of Experiments:** Students should use the commercial software or programmes from the text-books or self-developed programs, to verify the results obtained by manual calculations. The input data and output results of the problem solved using the computer programs should be included in the Journal. The proposed list is given below:

1. Any two problems using bar element
2. Any two problems using truss element
3. Any two problems using CST element
4. Any two problem using axisymmetric element
5. Any one problem of free vibration analysis using bar element
6. Any one problem on steady state heat conduction

While performing the analysis the students should understand the concepts of selection of element type, meshing and convergence of solution.

**b) Course Project:**

A group of not more than four students, shall do Finite Element Analysis of any mechanical engineering element /system, which involves element selection, assigning properties, meshing, assigning loads, and boundary conditions, analysis and result interpretation.

The distribution of marks for term work shall be as follows:

Part a:	15 marks.
Part b:	05 marks.
Attendance:	05 Marks.

**End Semester Practical/Oral examination**

1. Pair of Internal and External Examiner should conduct practical/viva based on contents
2. Duration of practical examination is 2 hour
3. Distribution of marks for practical/viva examination shall be as follows:
  - a) Practical performance .....**15** marks
  - b) Oral .....**10** marks
4. Evaluation of practical examination to be done based on the experiment performed and the output of the experiments during practical examination.
5. Students work along with evaluation report to be preserved till the next examination

Course Code	Course/Subject Name	Credits
<b>MEL604</b>	<b>Refrigeration and Air Conditioning TW/Practical</b>	<b>1</b>

### Objectives

1. To study operating principles of Vapour Compression system
2. To study components of refrigeration and air conditioning systems
3. To study controls and applications of refrigeration and air conditioning

**Outcomes:** Learner will be able to...

1. Demonstrate fundamental principles of refrigeration and air conditioning
2. Identify and locate various important components of the refrigeration and air conditioning system
3. Represent various refrigeration and air conditioning processes using psychometric chart
4. Operate and maintain refrigeration system
5. Operate and maintain air conditioning system
6. Simulate VCRS

### Part A: List of Experiments

Trial on window air conditioner or Air Conditioning Test Rig

Trial on water cooler/Refrigeration Test Rig

Trial on Ice Plant

Trial on cooling tower

### Part B: Demonstrations/Reports/Assignments/Simulations

Demonstration of domestic refrigerator along with wiring diagram

Demonstration of leak detection, evacuation and charging of refrigerant

Report on different protocols to regulate global warming

Visit report of Refrigeration establishment like Cold storage plant or ice plant or air-conditioning plant

Assignment on humidification and dehumidification, heating and cooling, mixing of two air streams

Steady state Simulation of VCR system with developed code or any analytical software

### Term work

Term work shall consists of minimum Three Laboratory Experiments, at least one demonstration exercise, Industrial Visit Report, at least one assignment consisting of numerical based on Refrigeration and Air Conditioning and one simulation exercise on VCR

The distribution of marks for term work shall be as follows:

Part a:	15 marks.
Part b:	05 marks.
Attendance:	05 Marks.

### End Semester Practical/Oral examination:

1. Pair of Internal and External Examiner should conduct practical/viva based on contents
2. Practical examination (in a group of not more than 5 students) duration is 2 hours
3. Distribution of marks for practical/viva examination shall be as follows:
  - a. Practical performance .....**15** marks
  - b. Oral .....**10** marks
4. Evaluation of practical examination to be done based on the experiment performed and the output of the experiments during practical examination.
5. Students work along with evaluation report to be preserved till the next examination

Subject Code	Subject Name	Credits
<b>MEL 605</b>	<b>Mechatronics Lab</b>	<b>01</b>

### Objectives

1. To study sensors and actuators
2. To study control systems
3. To study automation

### Outcomes: Learner will be able to...

1. Demonstrate implementation of interfacing sensors and actuators using microcontrollers
2. Demonstrate of interfacing various utilities with microcontrollers
3. Demonstrate discrete control system using PLC microcontroller
4. Design and develop a control system for specific use
5. Implement program to PLC system and demonstrate its application
6. Develop pneumatic circuits for a specific system

The laboratory experiments should be based on the following

### **Group 1: Sensors & Actuators**

1. Theoretical & Experimental Implementation of Interfacing of Sensors using microcontroller and determination of sensor characteristics such as Static Characteristics (Sensitivity, Accuracy, Range, Resolution etc.), Dynamic Characteristics (Transient Response and Frequency Response)
2. Measurement and Calibration of Load / Force (*It is suggested to determine all characteristics of sensor mentioned in previous experiments*)
3. Measurement, Calibration and Comparison of Temperature Sensors (Thermocouple, RTD and Thermistor) (*It is suggested to determine all characteristics of sensor mentioned in previous experiments*)
4. Interfacing of Stepper Motor with microcontroller and its programming for Rotational or XY table (*It is suggested to program to vary the position of rotary or XY table and compare the positioning accuracy using standard calibrated angular or linear sensor*)
5. Interfacing of DC Motor with microcontroller and its programming for characterization of DC motor setup ( *It is suggested to program to vary the speed of DC motor and determine its load-speed characteristics* )
6. Interfacing of Water Heater with microcontroller and its programming for determination of its transient and steady state characteristics (*It is suggested to program to vary the input current to heater and determine its transient and steady state characteristics*)

### **Group 2: Control Systems**

1. Experimental demonstration of Discrete control system using PLC microcontroller using standard PLC demo setup (Bottle filling Machine, Traffic Light Signal, Water heater and its stirring System etc.).  
*(here it is suggested to carry out ladder programming and demonstrate its operation)*
2. System Identification of Spring Mass Damper System for step input & harmonic input and determination of poles and zeros of system. *( Spring Mass Damper setup with all required position sensors mounted is to be characterized for step input, it is suggested to determine transfer function (i.e. input output relation) of the setup and plotting its transient and frequency response (Bode plot))*
3. Design & Experimental Implementation of PID control strategy for Spring Mass Damper Setup to control precisely position of mass. *(it is suggested to conduct experimental study on effect of variation of controller parameters on its transient characteristics also to study the changes in poles and zeros of system).*
4. Design & Experimental Implementation of PID control strategy for DC motor speed control under varying loading conditions and effect of variation of load is to be studied.
5. Design & Experimental implementation of PID control strategy for Real Time Temperature Control of furnace *(it is suggested to conduct experimental study on effect of variation of controller parameters on its transient characteristics also to study the changes in poles and zeros of system).*
6. Modeling and design of control system for quarter car suspension model using any suitable modeling and analysis software.

### **Group 3: Automation**

1. Real time Logic implementation for traffic Control demo setup and it is necessary to carry out ladder programming and implement program to PLC system and demonstrate its operations
2. IOT: Real time interfacing of sensors (temperature, humidity, position, level etc.) and actuator (stepper motor, dc motor, servo motor etc.) with microcontroller and Ethernet shield and controlling the actuator and monitoring of sensor output remotely using internet.
3. Robotics: Real Time demonstration of line following robot using standard robotic kit
4. Demonstration and study of functions of components of robotics arm.
5. Visualization of DH parameters in Roboanalyzer. (\*Roboanalyzer is free software developed by IIT Delhi, available on [www.roboanalyzer.com](http://www.roboanalyzer.com))
6. Designing sequential operation for two cylinders using electro-hydraulic circuits
7. Designing sequential operation for two cylinders using electro- pneumatic circuits
8. Development of pneumatic circuits to understand pneumatic components and their working

**Term work**

Term work shall consists of minimum Nine Experiments, Three from each group mentioned above

The distribution of marks for term work shall be as follows:

Laboratory Work:	20 marks.
Attendance:	05 Marks.

**End Semester Practical/Oral examination:**

1. Pair of Internal and External Examiner should conduct practical/oral based on contents
2. Practical examination (in a group of not more than 4 students) duration is 2 hours
3. Distribution of marks for practical/Oral examination shall be as follows:
  - a. Practical performance .....**15** marks
  - b. Oral .....**10** marks
4. Evaluation of practical examination to be done based on the experiment performed and the output of the experiments during practical examination.
5. Students work along with evaluation report to be preserved till the next examination