# Vidyavardhini's College of Engineering and Technology Dept of Electronics and Telecommunication Engineering <br> Sub: Digital Communication (R-2016) <br> Sem-V <br> Subject code: ECC 502 

1. Which of the following statements are correct for probability mass function, $f(x)=P(X=x)$, of a discrete random variable X has the following properties:
a) All probabilities are positive: $\mathrm{fx}(\mathrm{x}) \geq 0$.
b) Any event in the distribution has a probability of happening of between 0 and 1 (e.g. $0 \%$ and $100 \%$ ).
c) The sum of all probabilities is $100 \%$ (i.e. 1 as a decimal): $\Sigma \mathrm{fx}(\mathrm{x})=1$.
i) a and b
ii) b and c
iii) a, b and c
iv) None of the above
2. In probability theories, the events which can never occur together are classified as
i) collectively exclusive events
ii) mutually exhaustive events
iii) mutually exclusive events
iv) collectively exhaustive events
3. Let $X$ be a random variable with probability distribution function $f(x)=0.2$ for $|x|<1$
$=0.1$ for $1<|\mathrm{x}|<4$
$=0$ otherwise
The probability $\mathrm{P}(0.5<\mathrm{x}<5)$ is $\qquad$
i) 0.3
ii) 0.5
iii) 0.4
iv) 0.8
4. Variance of a random variable X is given by $\qquad$
a) $E(X)$
b) $E\left(X^{2}\right)$
c) $E\left(X^{2}\right)-(E(X))^{2}$
d) $(\mathrm{E}(\mathrm{X}))^{2}$
5. For random process $X=6$ and $R x x(t, t+t)=36+25 \exp (|t|)$. Consider following statements:
(i) $\mathrm{X}(\mathrm{t})$ is first order stationary.
(ii) $\mathrm{X}(\mathrm{t})$ has total average power of 36 W .
(iii) $\mathrm{X}(\mathrm{t})$ is a wide sense stationary.
(iv) $\mathrm{X}(\mathrm{t})$ has a periodic component.

Which of the following is true?
a) 1,2, and 4
b) 2,3 , and 4
c) 2 and 3
d) only 3
6. A random process is defined by $\mathrm{X}(\mathrm{t})+\mathrm{A}$ where A is continuous random variable uniformly distributed on
$(0,1)$. The auto correlation function and mean of the process is
a) $1 / 2 \& 1 / 3$
b) $1 / 3 \& 1 / 2$
c) $1 \& 1 / 2$
d) $1 / 2 \& 1$
7. According to Shannon Hartley theorem on channel capacity
(a) $\mathrm{C} / \mathrm{B}=\log _{2}(1+\mathrm{S} / \mathrm{N})$
(b) $\mathrm{C} / \mathrm{B}=\log _{2}\left(1+\mathrm{S} / \mathrm{N}_{0}\right)$
(c) $\mathrm{C} / \mathrm{B}=\log _{10}(1+\mathrm{S} / \mathrm{N})$
(d) $\mathrm{C} / \mathrm{B}=\log 10(1+\mathrm{S} / \mathrm{N} 0)$
8. Relation between probability $\mathrm{Pk}_{\mathrm{k}}$ and Information Ik is
(a) $\mathrm{I}_{\mathrm{k}}=\log _{10}\left(1 / \mathrm{P}_{\mathrm{k}}\right)$
(b) $\mathrm{I}_{\mathrm{k}}=\log _{2}\left(1 / \mathrm{P}_{\mathrm{k}}\right)$
(c) $\mathrm{I}_{\mathrm{k}}=10 \log _{2}\left(1 / \mathrm{P}_{\mathrm{k}}\right)$
(d) $\mathrm{Ik}=10 \log 10(1 / \mathrm{Pk})$
9. Shannon's theorem on channel capacity
(a) $\mathrm{R} \leq \mathrm{C}$
(b) $\mathrm{R} \geq \mathrm{C}$
(c) $\mathrm{R}=\mathrm{C}$
(d) $\mathrm{R} \times \mathrm{C}$
10. Given below is a parity check matrix of a linear block code.

$$
\begin{array}{r}
\mathrm{H}=\begin{array}{llllll}
1 & 1 & 1 & 1 & 1 & 1 \\
1 & 1 & 0 & 1 & 1 & 0 \\
0 & 1 & 1 & 0 & 0 & 1 \\
0 & 1 & 0 & 0 & 0 & 0
\end{array}
\end{array}
$$

This corresponds to a
i) $(6,3)$ linear block code
ii) $(6,4)$ linear block code
iii) $(6,2)$ linear block code
iv) $(2,6)$ linear block code
11. How error detection and correction is done?
a) By passing it through equalizer
b) By passing it through filter
c) By amplifying it
d) By adding redundancy bits
12. A cyclic code can be generated using
a) Generator polynomial
b) Generator matrix
c) Generator polynomial \& matrix
d) None of the mentioned
13. The number of k bit shift over which a single information bit influences the encoder output is given by
a) Code rate
b) Constraint length
c) Code length
d) Code weight
14. The error correcting capability of a code scheme increases as the
a) Number of channel symbols per information bit increases
b) Bandwidth increases
c) Information per bit increases
d) All of the mentioned
15. Which is called as on-off keying?
a) Amplitude shift keying
b) Uni-polar PAM
c) Amplitude shift keying \& Uni-polar PAM
d) FSK
16. Which has same probability of error?
a) BPSK and QPSK
b) BPSK and ASK
c) BPSK and PAM
d) BPSK and QAM
17. Which statements are false
a) Binary phase shift keying is a straightforward modulation scheme that can transfer two bits per symbol.
b) Quadrature phase shift keying is more complex but doubles the data rate (or achieves the same data rate with half the bandwidth).
c) QPSK has the same Bandwidth as that of BPSK.
d) Differential QPSK uses the phase difference between adjacent symbols to avoid problems associated with a lack of phase synchronization between the transmitter and receiver.
i)a, b, c and d
ii) b,c and d
iii) a and c
iv) All of the above
18. In which system, bit stream is portioned into even and odd stream?
a) BPSK
b) MSK
c) QPSK
d) FSK
19. The limit which represents the threshold $\mathrm{Eb} / \mathrm{N} 0$ value below which reliable communication cannot be maintained is called as
a) Probability limit
b) Error limit
c) Shannon limit
d) Communication limit
20. The non coherent FSK needs $\qquad$ $\mathrm{Eb} / \mathrm{N} 0$ than coherent FSK.
a) 1 db more
b) 1 db less
c) 3 db more
d) 3 db less
21. A Gaussian distribution into the non linear envelope detector yields
a) Rayleigh distribution
b) Normal distribution
c) Poisson distribution
d) Binary distribution
22. The process of converting coded output into electrical pulses or waveforms for transmission is called
(a) Line coding
(b) Amplitude modulation
(c) FSK
(d) Filtering
23. In a uni-polar RZ format,
(a) The waveform has zero value for symbol ' 0 '
(b) The waveform has A volts for symbol ' 0 '
(c) The waveform has positive and negative values for ' 1 ' and ' 0 ' symbol respectively
(d) The waveform has - A volts for symbol ' 0 '
24. Matched filters characteristic is
(a) To maximize Signal to noise ratio even for non-Gaussian noise
(b) It gives the output as signal energy in the presence of noise
(c) They are used for signal amplification.
(d) None of the above
25. Matched filters may be used

To estimate the frequency of the received signal In parameter de-estimation problems
To calculate the distance of the object
To filter the noise

