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4<sup>TH</sup> APRIL, 2020**



**Organized by:**

Vidyavardhini's College of  
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K.T. Marg, Vasai (W) - 401202

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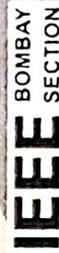
**In Association With:**

BJIT - BVICAM's International Journal of Information  
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**VNC - 2020 TASU**

143\_Design and development of inline two wheeler self-balancing electric bike

### About us:

Vidyavardhini means a Body committed to enhancement of Knowledge. Vidyavardhini was established as a registered society in 1970 by late Padmeshri H. G. alias Bhausaheb Vartak for the noble cause of education in rural areas.

Vidyavardhini's College of Engineering and Technology, Vasai is located on the sprawling campus of Vidyavardhini, spread over an area of 12.27 acres. It is a short, two minutes walk from Vasai Road (W) Railway Station. The college is also accessible by road from Mumbai.

Vidyavardhini Society received approval from AICTE to start the new college of Engineering & Technology with effect from July, 1994. The college is affiliated to the University of Mumbai for the four year degree program leading to the degree of Bachelor of Engineering in six branches.

### Objective of VNC 2020 TASU

Technology has always been potential tool for simplifying the way we do things. Present time demands directing the technological advancements towards addressing societal challenges such as improving health care, education environment, sanitation, agriculture, smart city, etc., VNC 2020 TASU aims to provide an opportunity to researchers, academicians, Industrialist and students to interact and share their ideologies and contributions made for social upliftment with the aid of technological advancements.

### Call for paper

We welcome submission in following area

1. Sustainable Computing
  2. High Performance Computing
  3. High Speed Networking and Information Security
  4. Software Engineering and Emerging Technologies
  5. Mathematical, Experimental, Computational and AI, IoT Techniques in Mechanical Engg.
  6. Industrial Engg., ERP, MRP, SCM
  7. Renewable Energy Technologies
  8. Pollution control and Waste Management
  9. Advances in Structural engineering
  10. Present geotechnical practices
  11. Present practices in construction management
  12. Recent developments in Instrumentation, control and automation
  13. Embedded Systems, IoT and VLSI Design
  14. Optical and Wireless Communication for NGN
  15. Antenna and Microwave Devices
- Any other relevant topics

### Important Dates:

- Submission of full length paper 15<sup>th</sup> Feb 2020
- Paper Acceptance Notification 22<sup>nd</sup> Feb 2020
- Submission of Final Version of Paper 29<sup>th</sup> Feb 2020
- Registration Deadline 5<sup>th</sup> March 2020
- PPT Submission 20<sup>th</sup> March 2020
- Conference 4<sup>th</sup> April 2020

### Registration Fee Details:

Category of Delegates / Authors	Indian Authors & Delegates (in INR)
Full Time Students (UG)	1,500.00
Teachers/ Research Scholars/ PG students	2,500.00
Industry	3,500.00

### Publication Information

Proceedings of VNC - 2020 TASU will be published with ISBN number

1. Selected Papers will be published in International Journal of Information Technology, Published by Springer Nature, ISSN: 2511-2104 (Print Version), ISSN: 2511-2112 (Electronic Version)
2. All papers will be published in IJERT, ISSN: 2278-0181

### Paper Submission:

Paper submission should be made strictly via Easy Chair the submission link for VNC 2020 "TASU":

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**\*Best paper award  
for each track\***

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# DESIGN AND DEVELOPMENT OF INLINE TWO WHEELER SELF-BALANCING ELECTRIC BIKE

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**Abstract-** The two wheel vehicles during operation face the issue of balancing especially with untrained rider. Lot of time and fuel could be wasted by learners of the two wheel vehicle in balancing of the vehicle during training period. So, the main objective of this work is to design and develop a self-balancing electric two wheel vehicle which can balance itself with or without rider even vehicle may be in motion or stationary. The controller has two different objectives: to sense the velocity of vehicle in order to operate the actuator for manipulation of rake angle and other is the angle sensor to manipulate the steering angle with respect to vertical. The simultaneous adjustment of these two sensors will maintain the motorcycle stable. The actual set up will be experimented further aiming to balance the vehicle in different condition of loads.

**Keywords-** Self-balancing; electric vehicle; stability control; trajectory control.

## I. INTRODUCTION

The bike which can balance itself is very popular project in robotics and engineering. There is lot of work going on about balancing bike and some are already done and a lot of work still need to done. The following section is our literature review on this particular topic.

In 1903, an Irish-Australian inventor Louis Grennan was first to patent a gyroscopic balancing a gyroscopic balancing vehicle.

In 1912, Russian inventor Dr.Pyotr Shilovsky in collaboration with Louis Grennan developed and designed a two wheel car with gyroscope sitting in the middle of the body of car for maintaining stabilizing force.

The self-balancing and two wheel robot SEGWAY HT is commercially available and it is invented by Dean Kamen who has design more than 140 systems. In CES (Consumer Electronics Show) 2017 Honda unveiled the 'Riding Assist' technology which is the best example and working model of self balancing bike.

Design:

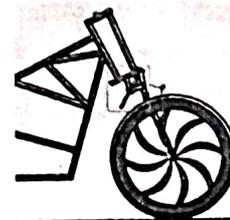
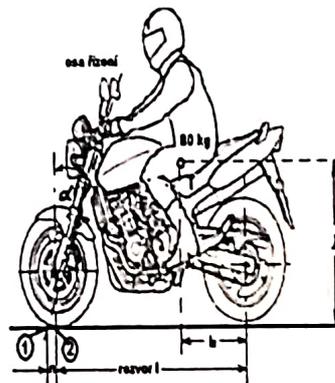


Fig. 1. Chassis Geometry